Constructing Asymptotically Constrained Systems by adjusting ADM/BSSN equations

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Who is HS?

PhD @ Waseda Univ. (supervised by Keiichi Maeda)
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Refs:

Ashtekar variables	PRL **82** (1999) 263, PRD **60** (1999) 101502, IJMPD **9** (2000) 13, CQG **17** (2000) 4799, CQG **18** (2001) 441
ADM variables	PRD **63** (2001) 120419, CQG **19** (2002) 1027
BSSN variables	gr-qc/0204002 (PRD in print)
general	gr-qc/0209106 and gr-qc/0209111 (review)

@ Caltech, October 10, 2002

Outline

- Three approaches: ADM/BSSN, hyperbolic formulation, attractor systems
- Proposals : **A unified treatment as Adjusted Systems**

  Analytic Support: Constraint Propagation eqs.
  Some predictions and Numerical experiments

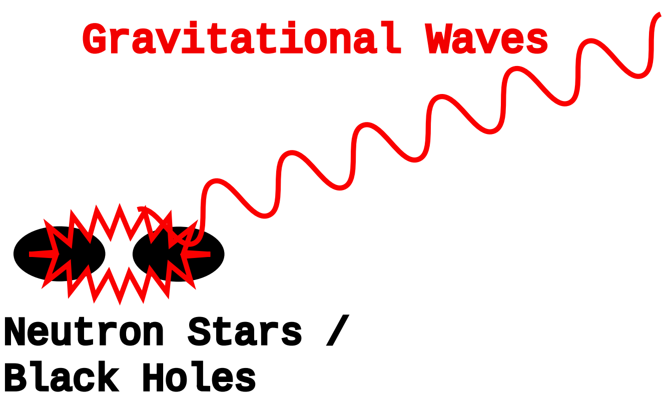
Plan of the talk

1. Introduction
2. Three approaches
   (1) Arnowitt-Deser-Misner / Baumgarte-Shapiro-Shibata-Nakamura
   (2) Hyperbolic formulations
   (3) Attractor systems – "Adjusted Systems"
3. Adjusted ADM systems
   Flat background
   Schwarzschild background
4. Adjusted BSSN systems
   Flat background
5. Summary

1 Numerical Relativity and "Formulation" Problem

Numerical Relativity – Necessary for unveiling the nature of strong gravity

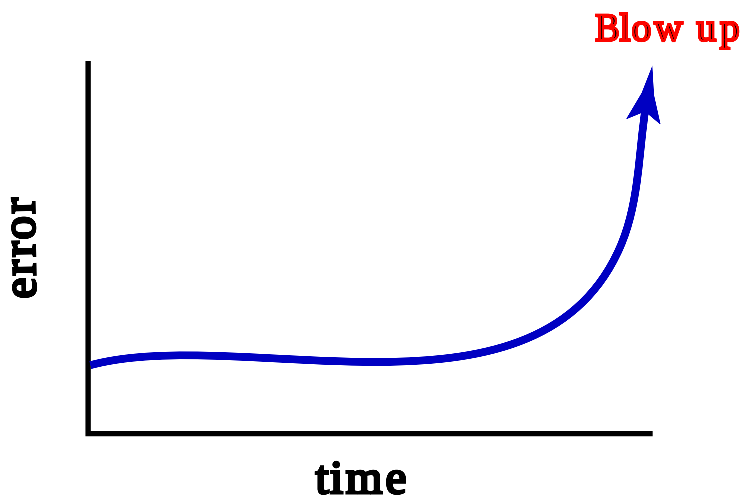
- Gravitational Wave from colliding Black Holes, Neutron Stars, Supernovae, ...
- Relativistic Phenomena like Cosmology, Active Galactic Nuclei, ...
- Mathematical feedbacks to Singularity, Exact Solutions, Chaotic behaviors, ...
- Laboratory of Gravitational theories, Higher dimensional models, ...

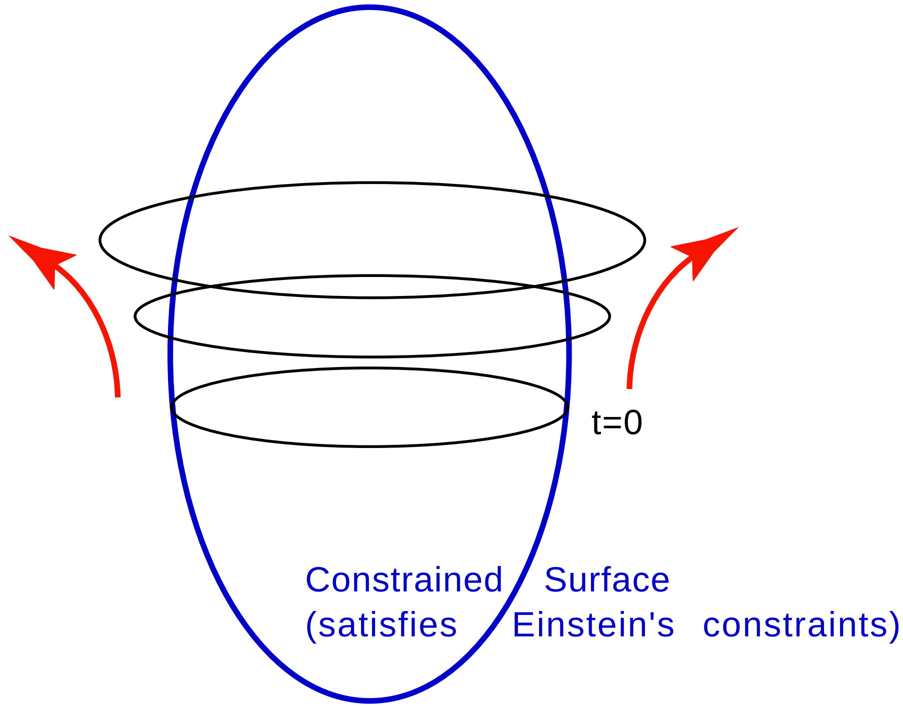


LIGO/VIRGO/GEO/TAMA, ...

Best formulation of the Einstein eqs. for long-term stable & accurate simulation?

Many (too many) trials and errors, not yet a definit recipe.





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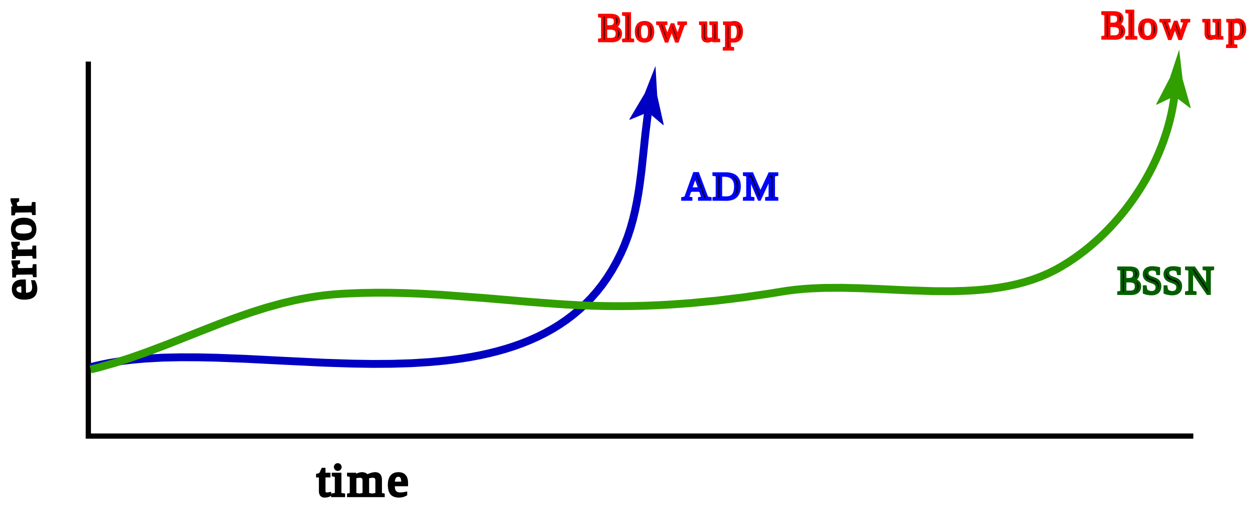


Mathematically equivalent formulations, but differ in its stability!

strategy 0: Arnowitt-Deser-Misner formulation

strategy 1: Shibata-Nakamura's (Baumgarte-Shapiro's) modifications to the standard ADM

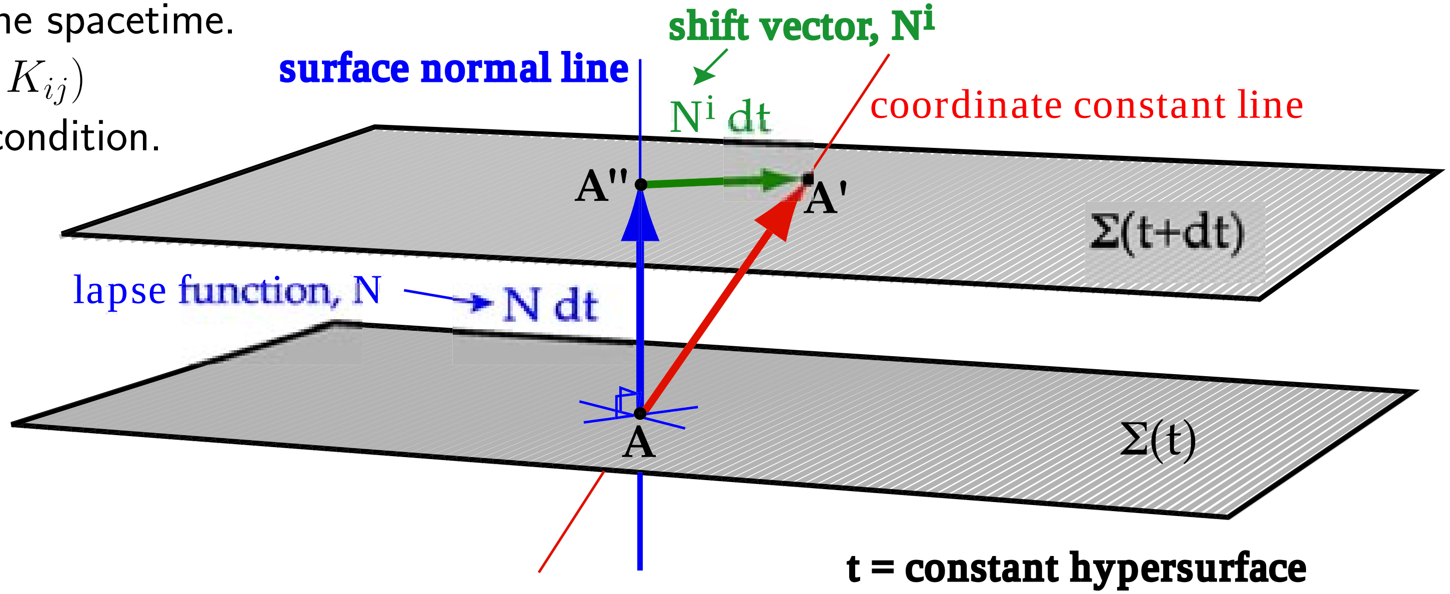
strategy 2: Apply a formulation which reveals a hyperbolicity explicitly

strategy 3: Formulate a system which is "asymptotically constrained" against a violation of constraints

By adding constraints in RHS, we can kill error-growing modes
$\Rightarrow$ How can we understand the features systematically?

strategy 0 The standard approach :: Arnowitt-Deser-Misner (ADM) formulation (1962)

3+1 decomposition of the spacetime.
Evolve 12 variables (γ_{ij}, K_{ij})
with a choice of gauge condition.



	Maxwell eqs.	ADM Einstein eq.
constraints	div $\mathbf{E} = 4\pi\rho$ div $\mathbf{B} = 0$	$^{(3)}R + (\mathrm{tr}K)^2 - K_{ij}K^{ij} = 2\kappa\rho_H + 2\Lambda$ $D_j K^j{}_i - D_i \mathrm{tr}K = \kappa J_i$
evolution eqs.	$\frac{1}{c}\partial_t \mathbf{E} = \text{rot } \mathbf{B} - \frac{4\pi}{c}\mathbf{j}$ $\frac{1}{c}\partial_t \mathbf{B} = -\text{rot } \mathbf{E}$	$\partial_t \gamma_{ij} = -2NK_{ij} + D_j N_i + D_i N_j,$ $\partial_t K_{ij} = N({}^{(3)}R_{ij} + \mathrm{tr}K K_{ij}) - 2NK_{il}K^l{}_j - D_i D_j N$ $+ (D_j N^m)K_{mi} + (D_i N^m)K_{mj} + N^m D_m K_{ij} - N\gamma_{ij}\Lambda$ $- \kappa\alpha\{S_{ij} + \frac{1}{2}\gamma_{ij}(\rho_H - \mathrm{tr}S)\}$

strategy 1 Shibata-Nakamura's (Baumgarte-Shapiro's) modifications to the standard ADM

– define new variables (ϕ, $\tilde{\gamma}_{ij}$, K, $\tilde{A}_{ij}$, $\tilde{\Gamma}^i$), instead of the ADM's (γ_{ij}, K_{ij}) where

$$\tilde{\gamma}_{ij} \equiv e^{-4\phi}\gamma_{ij}, \qquad \tilde{A}_{ij} \equiv e^{-4\phi}(K_{ij} - (1/3)\gamma_{ij}K), \qquad \tilde{\Gamma}^i \equiv \tilde{\Gamma}^i_{jk}\tilde{\gamma}^{jk},$$

use momentum constraint in Γ^i-eq., and impose $\det\tilde{\gamma}_{ij} = 1$ during the evolutions.

– The set of evolution equations become

$$\begin{aligned}
(\partial_t - \mathcal{L}_\beta)\phi &= -(1/6)\alpha K, \\
(\partial_t - \mathcal{L}_\beta)\tilde{\gamma}_{ij} &= -2\alpha\tilde{A}_{ij}, \\
(\partial_t - \mathcal{L}_\beta)K &= \alpha\tilde{A}_{ij}\tilde{A}^{ij} + (1/3)\alpha K^2 - \gamma^{ij}(\nabla_i\nabla_j\alpha), \\
(\partial_t - \mathcal{L}_\beta)\tilde{A}_{ij} &= -e^{-4\phi}(\nabla_i\nabla_j\alpha)^{TF} + e^{-4\phi}\alpha R^{(3)}_{ij} - e^{-4\phi}\alpha(1/3)\gamma_{ij}R^{(3)} + \alpha(K\tilde{A}_{ij} - 2\tilde{A}_{ik}\tilde{A}^k{}_j) \\
\partial_t\tilde{\Gamma}^i &= -2(\partial_j\alpha)\tilde{A}^{ij} - (4/3)\alpha(\partial_j K)\tilde{\gamma}^{ij} + 12\alpha\tilde{A}^{ji}(\partial_j\phi) - 2\alpha\tilde{A}_k{}^j(\partial_j\tilde{\gamma}^{ik}) - 2\alpha\tilde{\Gamma}^k{}_{lj}\tilde{A}^j{}_k\tilde{\gamma}^{il} \\
&\quad -\partial_j\left(\beta^k\partial_k\tilde{\gamma}^{ij} - \tilde{\gamma}^{kj}(\partial_k\beta^i) - \tilde{\gamma}^{ki}(\partial_k\beta^j) + (2/3)\tilde{\gamma}^{ij}(\partial_k\beta^k)\right)
\end{aligned}$$

$$\begin{aligned}
R_{ij} &= \partial_k\Gamma^k_{ij} - \partial_i\Gamma^k_{kj} + \Gamma^m_{ij}\Gamma^k_{mk} - \Gamma^m_{kj}\Gamma^k_{mi} =: \tilde{R}_{ij} + R^\phi_{ij} \\
&\quad R^\phi_{ij} = -2\tilde{D}_i\tilde{D}_j\phi - 2\tilde{g}_{ij}\tilde{D}^l\tilde{D}_l\phi + 4(\tilde{D}_i\phi)(\tilde{D}_j\phi) - 4\tilde{g}_{ij}(\tilde{D}^l\phi)(\tilde{D}_l\phi) \\
&\quad \tilde{R}_{ij} = -(1/2)\tilde{g}^{lm}\partial_{lm}\tilde{g}_{ij} + \tilde{g}_{k(i}\partial_{j)}\tilde{\Gamma}^k + \tilde{\Gamma}^k\tilde{\Gamma}_{(ij)k} + 2\tilde{g}^{lm}\tilde{\Gamma}^k_{l(i}\tilde{\Gamma}_{j)km} + \tilde{g}lm\tilde{\Gamma}^k_{im}\tilde{\Gamma}_{klj}
\end{aligned}$$

– No explicit explanations why this formulation works better.

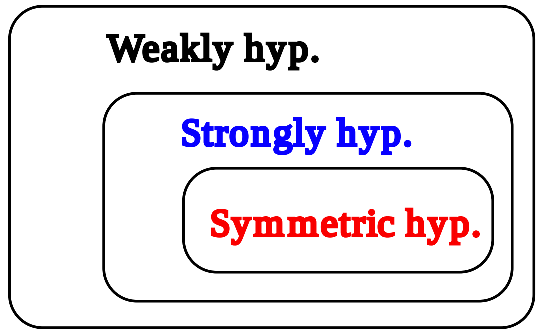
AEI group (2000): the replacement by momentum constraint is essential.

strategy 2 Apply a formulation which reveals a hyperbolicity explicitly.

For a first order partial differential equations on a vector u,

$$\partial_t \begin{bmatrix} u_1 \\ u_2 \\ \vdots \end{bmatrix} = \underbrace{\begin{bmatrix} & & \\ & A & \\ & & \end{bmatrix} \partial_x \begin{bmatrix} u_1 \\ u_2 \\ \vdots \end{bmatrix}}_{\text{characteristic part}} + \underbrace{B \begin{bmatrix} u_1 \\ u_2 \\ \vdots \end{bmatrix}}_{\text{lower order part}}$$

	if the eigenvalues of A are
weakly hyperbolic	all real.
strongly hyperbolic	all real and $\exists$ a complete set of eigenvalues.
symmetric hyperbolic	if A is real and symmetric (Hermitian).



Expectations

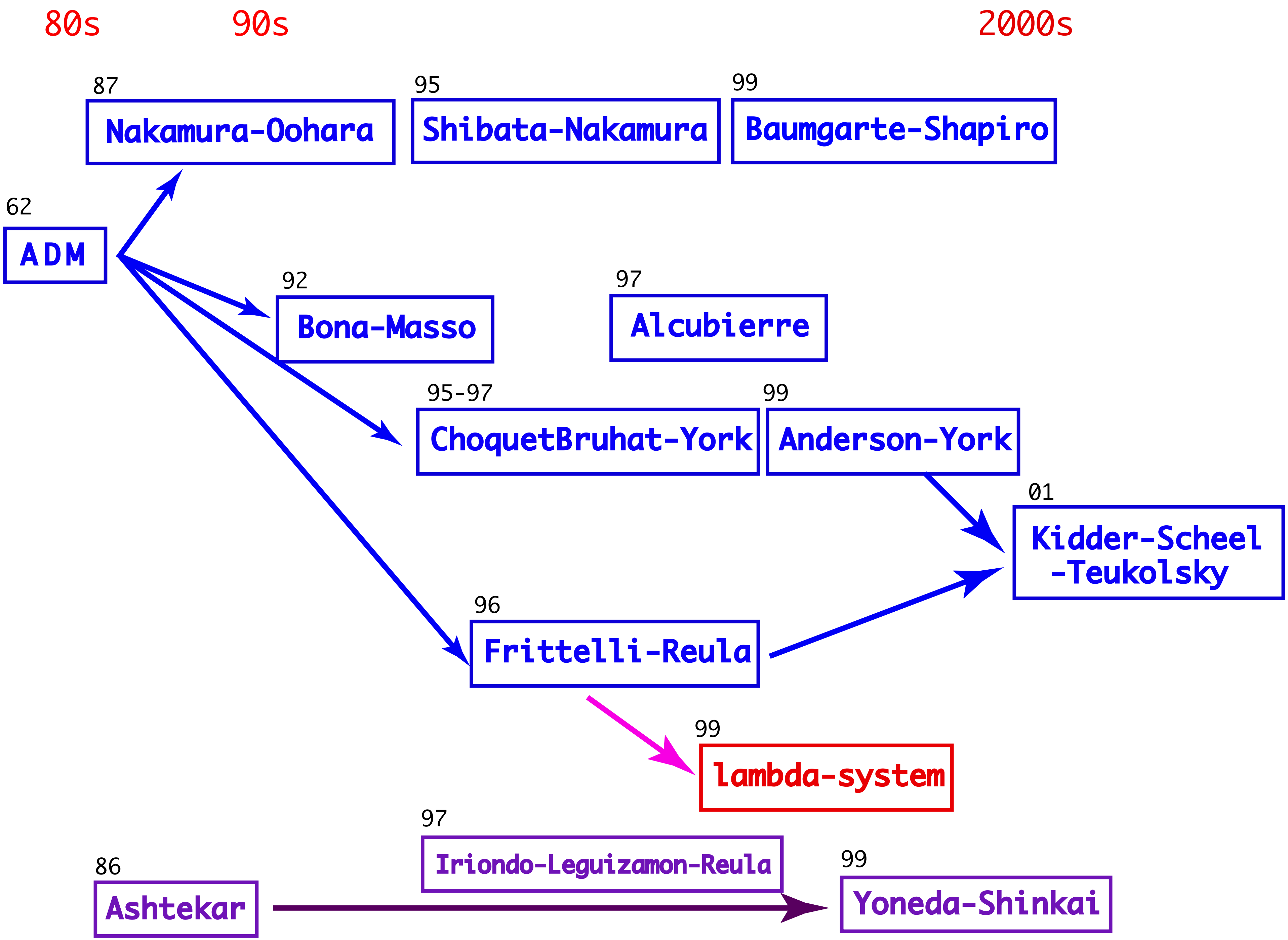
– Wellposed behaviour

symmetric hyperbolic system $\Longrightarrow$ WELL-POSED , $||u(t)|| \leq e^{\kappa t}||u(0)||$

– Better boundary treatments $\Longleftarrow \exists$ characteristic field.

– known numerical techniques in Newtonian hydrodynamics.

		formulations	numerical applications
(0) The standard ADM formulation			
	ADM	1962 Arnowitt-Deser-Misner [12, 78]	$\Rightarrow$ many
(1) The BSSN formulation			
	BSSN	1987 Nakamura et al [62, 63, 72]	$\Rightarrow$ 1987 Nakamura et al [62, 63]
			$\Rightarrow$ 1995 Shibata-Nakamura [72]
			$\Rightarrow$ 2002 Shibata-Uryu [73] etc
		1999 Baumgarte-Shapiro [15]	$\Rightarrow$ 1999 Baumgarte-Shapiro [15]
			$\Rightarrow$ 2000 Alcubierre et al [5, 7]
			$\Rightarrow$ 2001 Alcubierre et al [6] etc
		1999 Alcubierre et al [8]	
		1999 Frittelli-Reula [41]	
		2002 Laguna-Shoemaker [54]	$\Rightarrow$ 2002 Laguna-Shoemaker [54]
(2) The hyperbolic formulations			
	BM	1989 Bona-Massó [17, 18, 19]	$\Rightarrow$ 1995 Bona et al [19, 20, 21]
			$\Rightarrow$ 1997 Alcubierre, Massó [2, 4]
		1997 Bona et al [20]	$\Rightarrow$ 2002 Bardeen-Buchman [16]
		1999 Arbona et al [11]	
	CB-Y	1995 Choquet-Bruhat and York [31]	$\Rightarrow$ 1997 Scheel et al [69]
		1995 Abrahams et al [1]	$\Rightarrow$ 1998 Scheel et al [70]
		1999 Anderson-York [10]	$\Rightarrow$ 2002 Bardeen-Buchman [16]
	FR	1996 Frittelli-Reula [40]	$\Rightarrow$ 2000 Hern [43]
		1996 Stewart [79]	
	KST	2001 Kidder-Scheel-Teukolsky [51]	$\Rightarrow$ 2001 Kidder-Scheel-Teukolsky [51]
			$\Rightarrow$ 2002 Calabrese et al [26]
			$\Rightarrow$ 2002 Lindblom-Scheel [57]
		2002 Sarbach-Tiglio [68]	
	CFE	1981 Friedrich[35]	$\Rightarrow$ 1998 Frauendiener [34]
			$\Rightarrow$ 1999 Hübner [45]
	tetrad	1995 vanPutten-Eardley[84]	$\Rightarrow$ 1997 vanPutten [85]
	Ashtekar	1986 Ashtekar [13]	$\Rightarrow$ 2000 Shinkai-Yoneda [75]
		1997 Iriondo et al [47]	
		1999 Yoneda-Shinkai [90, 91]	$\Rightarrow$ 2000 Shinkai-Yoneda [75, 92]
(3) Asymptotically constrained formulations			
λ-system	to FR	1999 Brodbeck et al [23]	$\Rightarrow$ 2001 Siebel-Hübner [77]
	to Ashtekar	1999 Shinkai-Yoneda [74]	$\Rightarrow$ 2001 Yoneda-Shinkai [92]
adjusted	to ADM	1987 Detweiler [32]	$\Rightarrow$ 2001 Yoneda-Shinkai [93]
	to ADM	2001 Shinkai-Yoneda [93, 76]	$\Rightarrow$ 2002 Mexico NR Workshop [58]
	to BSSN	2002 Yoneda-Shinkai [94]	$\Rightarrow$ 2002 Mexico NR Workshop [58]
			$\Rightarrow$ 2002 Yo-Baumgarte-Shapiro [88]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ADM
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Nakamura-Oohara
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Iriondo-Leguizamon-Reula
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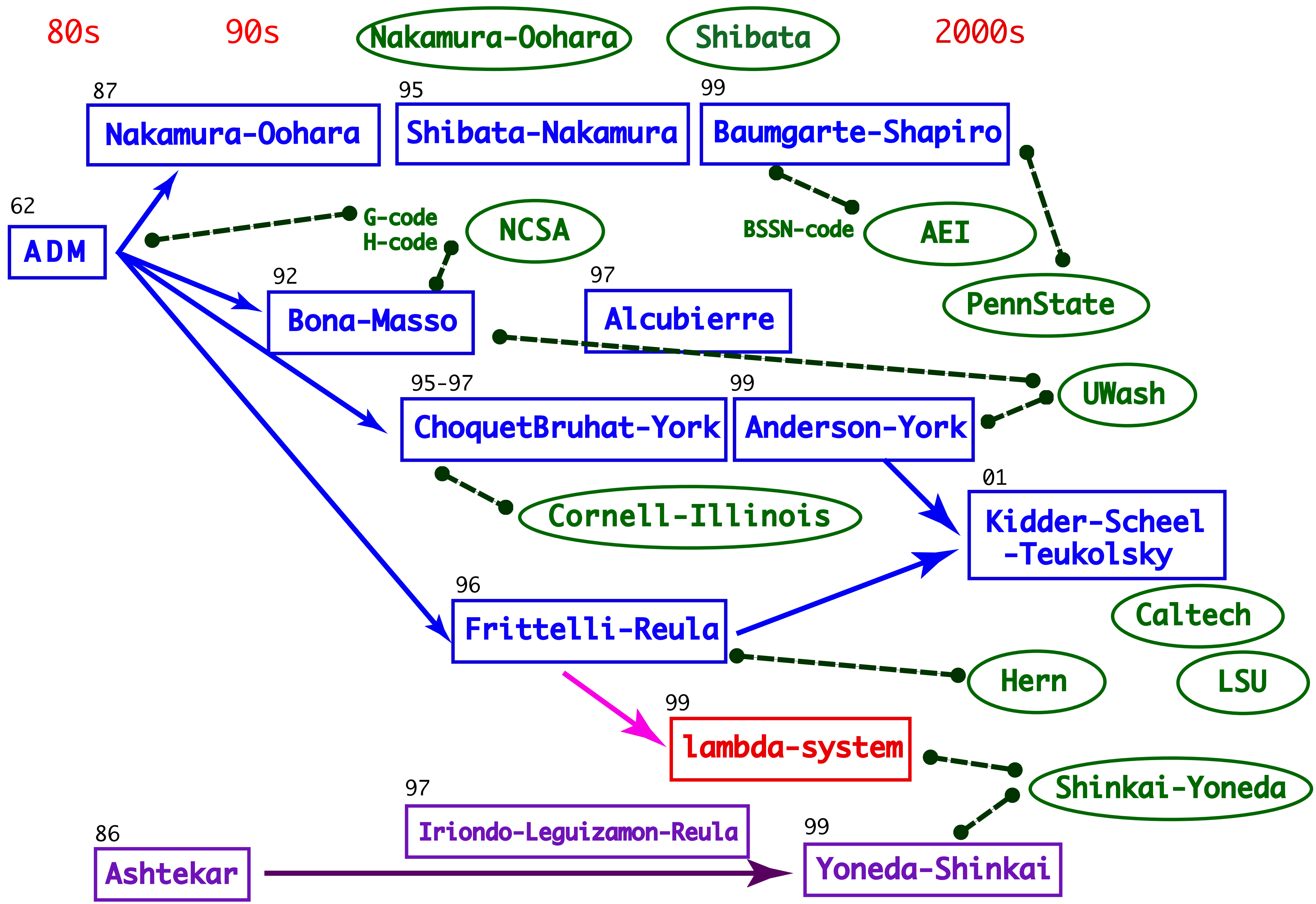
Yoneda-Shinkai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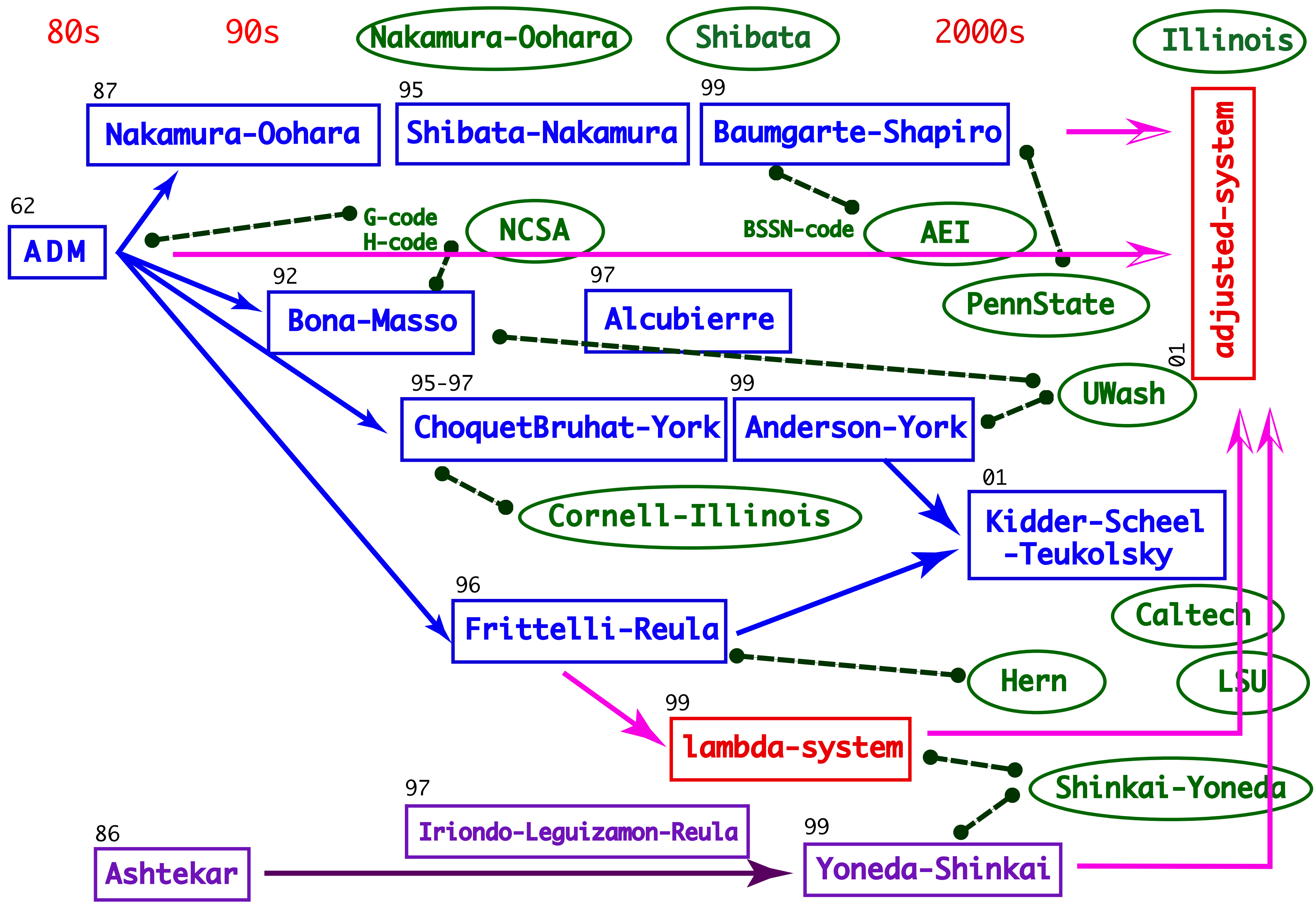
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strategy 2 Apply a formulation which reveals a hyperbolicity explicitly. (cont.)

symmetric hyperbolic $\subset$ strongly hyperbolic $\subset$ weakly hyperbolic systems,

- Are they actually helpful? — if so, which level of hyperbolicity is necessary?
- Under what conditions/situations the advantages will be observed?

Unfortunately, we do not have conclusive answers to them yet.

- Several numerical experiments indicate that the direction is NOT a full of success.
  - Earlier numerical comparisons reported the advantages of hyperbolic formulations, but they were against to the standard ADM formulation. [Cornell-Illinois, NCSA, ...]
  - Numerical evolutions are always **terminated with blow-ups**.
  - If the gauge functions are evolved with hyperbolic equations, then their finite propagation speeds may cause a pathological **shock formations** [Alcubierre].
  - No drastic numerical differences **between** three hyperbolic levels [HS Yoneda, Hern].
  - Proposed symmetric hyperbolic systems were not always the best one for numerics.

Of course, these statements only casted on a particular formulation, therefore we have to be careful not to over-announce the results.

strategy 2 Apply a formulation which reveals a hyperbolicity explicitly. (cont.)

- Remarks to hyperbolic formulations

  (a) Rigorous mathematical proofs of well-posedness of PDE are mostly for a simple symmetric or strongly hyperbolic systems. If the matrix components or coefficients depend dynamical variables (like in any versions of hyperbolized Einstein equations), almost nothing was proved in its general situations.

  (b) The statement of "stability" in the discussion of well-posedness means the bounded growth of the norm, and does not mean a decay of the norm in time evolution.

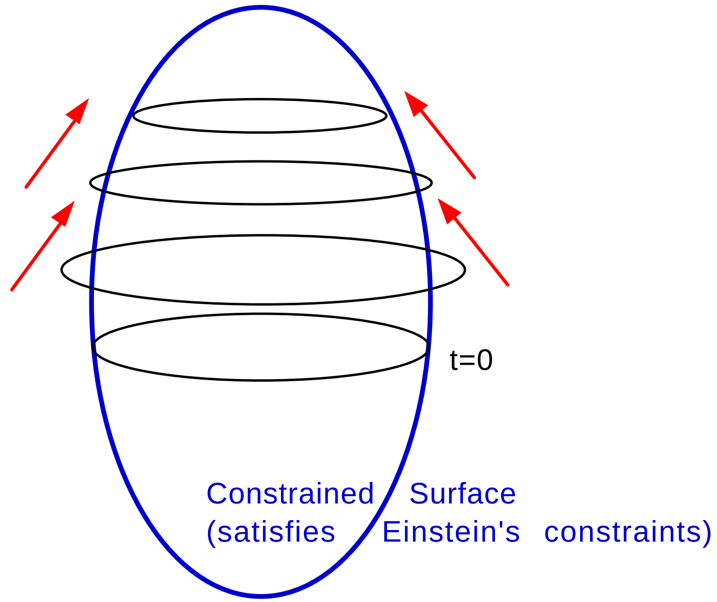
  (c) The discussion of hyperbolicity only uses the characteristic part of the evolution equations, and ignore the rest.

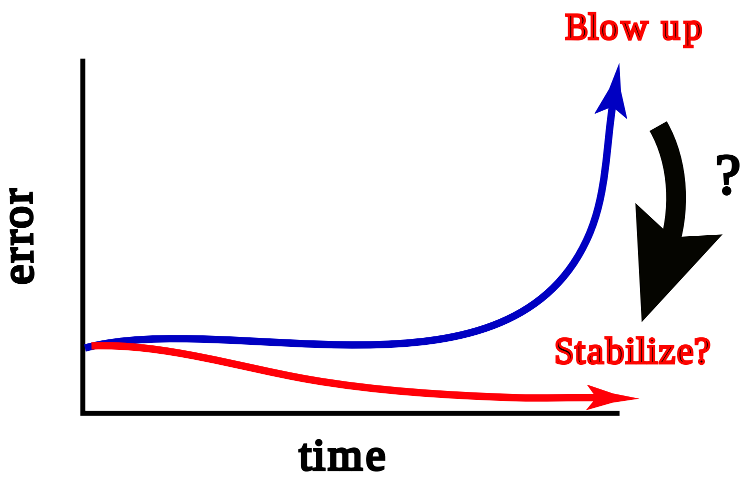
cf. Recent discussions

- KST formulation with "kinematic" parameters which enables us to reduce non-principal part.
- links to IBVP approach.
- relations between convergence behavior and levels of hyperbolicity.

strategy 3 Formulate a system which is "asymptotically constrained" against a violation of constraints

"Asymptotically Constrained System"– Constraint Surface as an Attractor





method 1: λ-system (Brodbeck et al, 2000)

- Add aritificial force to reduce the violation of constraints
- To be guaranteed if we apply the idea to a symmetric hyperbolic system.

method 2: Adjusted system (Yoneda HS, 2000, 2001)

- We can control the violation of constraints by adjusting constraints to EoM.
- Eigenvalue analysis of constraint propagation equations may prodict the violation of error.
- This idea is applicable even if the system is not symmetric hyperbolic. $\Rightarrow$ for the ADM/BSSN formulation, too!!

Idea of λ-system

Brodbeck, Frittelli, Hübner and Reula, JMP40(99)909

We expect a system that is robust for controlling the violation of constraints

Recipe

1. Prepare a symmetric hyperbolic evolution system $\partial_t u = J\partial_i u + K$
2. Introduce λ as an indicator of violation of constraint which obeys dissipative eqs. of motion $\partial_t \lambda = \alpha C - \beta \lambda$ $(\alpha \neq 0, \beta > 0)$
3. Take a set of (u, λ) as dynamical variables $\partial_t \begin{pmatrix} u \\ \lambda \end{pmatrix} \simeq \begin{pmatrix} A & 0 \\ F & 0 \end{pmatrix} \partial_i \begin{pmatrix} u \\ \lambda \end{pmatrix}$
4. Modify evolution eqs so as to form a symmetric hyperbolic system $\partial_t \begin{pmatrix} u \\ \lambda \end{pmatrix} = \begin{pmatrix} A & \bar{F} \\ F & 0 \end{pmatrix} \partial_i \begin{pmatrix} u \\ \lambda \end{pmatrix}$

Remarks

- BFHR used a sym. hyp. formulation by Frittelli-Reula [PRL76(96)4667]
- The version for the Ashtekar formulation by HS-Yoneda [PRD60(99)101502] for controlling the constraints or reality conditions or both.
- Succeeded in evolution of GW in planar spacetime using Ashtekar vars. [CQG18(2001)441]
- Do the recovered solutions represent true evolution? by Siebel-Hübner [PRD64(2001)024021]

Idea of "Adjusted system" and Our Conjecture

CQG18 (2001) 441, PRD 63 (2001) 120419, CQG 19 (2002) 1027

General Procedure

1. prepare a set of evolution eqs. $\partial_t u^a = f(u^a, \partial_b u^a, \cdots)$
2. add constraints in RHS $\partial_t u^a = f(u^a, \partial_b u^a, \cdots) \underbrace{+F(C^a, \partial_b C^a, \cdots)}$
3. choose appropriate $F(C^a, \partial_b C^a, \cdots)$ to make the system stable evolution

How to specify $F(C^a, \partial_b C^a, \cdots)$?

4. prepare constraint propagation eqs. $\partial_t C^a = g(C^a, \partial_b C^a, \cdots)$
5. and its adjusted version $\partial_t C^a = g(C^a, \partial_b C^a, \cdots) \underbrace{+G(C^a, \partial_b C^a, \cdots)}$
6. Fourier transform and evaluate eigenvalues $\partial_t \hat{C}^k = \underbrace{A(\hat{C}^a)}\, \hat{C}^k$

Conjecture: Evaluate eigenvalues of (Fourier-transformed) constraint propagation eqs.
If their (1) real part is non-positive, or (2) imaginary part is non-zero, then the system is more stable.

The Adjusted system (essentials):

Purpose: Control the violation of constraints by reformulating the system so as to have a constrained surface an attractor.

Procedure: Add a particular combination of constraints to the evolution equations, and adjust its multipliers.

Theoretical support: Eigenvalue analysis of the constraint propagation equations.

Advantages: Available even if the base system is not a symmetric hyperbolic.

Advantages: Keep the number of the variable same with the original system.

Conjecture on Constraint Amplification Factors (CAFs):

(A) If CAF has a negative real-part (the constraints are forced to be diminished), then we see more stable evolution than a system which has positive CAF.

(B) If CAF has a non-zero imaginary-part (the constraints are propagating away), then we see more stable evolution than a system which has zero CAF.

Example: the Maxwell equations

Yoneda HS, CQG 18 (2001) 441

Maxwell evolution equations.

$$\begin{aligned}\partial_t E_i &= c\epsilon_i{}^{jk}\partial_j B_k + P_i C_E + Q_i C_B,\\ \partial_t B_i &= -c\epsilon_i{}^{jk}\partial_j E_k + R_i C_E + S_i C_B,\\ &C_E = \partial_i E^i \approx 0, \quad C_B = \partial_i B^i \approx 0,\end{aligned}$$

$$\begin{cases}\text{sym. hyp} & \Leftrightarrow \quad P_i = Q_i = R_i = S_i = 0,\\ \text{strongly hyp} & \Leftrightarrow \quad (P_i - S_i)^2 + 4R_iQ_i > 0,\\ \text{weakly hyp} & \Leftrightarrow \quad (P_i - S_i)^2 + 4R_iQ_i \geq 0\end{cases}$$

Constraint propagation equations

$$\begin{aligned}\partial_t C_E &= (\partial_i P^i)C_E + P^i(\partial_i C_E) + (\partial_i Q^i)C_B + Q^i(\partial_i C_B),\\ \partial_t C_B &= (\partial_i R^i)C_E + R^i(\partial_i C_E) + (\partial_i S^i)C_B + S^i(\partial_i C_B),\end{aligned}$$

$$\begin{cases}\text{sym. hyp} & \Leftrightarrow \quad Q_i = R_i,\\ \text{strongly hyp} & \Leftrightarrow \quad (P_i - S_i)^2 + 4R_iQ_i > 0,\\ \text{weakly hyp} & \Leftrightarrow \quad (P_i - S_i)^2 + 4R_iQ_i \geq 0\end{cases}$$

CAFs?

$$\partial_t \begin{pmatrix}\hat{C}_E\\ \hat{C}_B\end{pmatrix} = \begin{pmatrix}\partial_i P^i + P^i k_i & \partial_i Q^i + Q^i k_i\\ \partial_i R^i + R^i k_i & \partial_i S^i + S^i k_i\end{pmatrix}\partial_l \begin{pmatrix}\hat{C}_E\\ \hat{C}_B\end{pmatrix} \approx \begin{pmatrix}P^i k_i & Q^i k_i\\ R^i k_i & S^i k_i\end{pmatrix}\begin{pmatrix}\hat{C}_E\\ \hat{C}_B\end{pmatrix} =: T\begin{pmatrix}\hat{C}_E\\ \hat{C}_B\end{pmatrix}$$

$$\Rightarrow \text{CAFs} = (P^i k_i + S^i k_i \pm \sqrt{(P^i k_i + S^i k_i)^2 + 4(Q^i k_i R^j k_j - P^i k_i S^j k_j)})/2$$

Therefore CAFs become negative-real when

$$P^i k_i + S^i k_i < 0, \qquad \text{and} \qquad Q^i k_i R^j k_j - P^i k_i S^j k_j < 0$$

Example: the Ashtekar equations

HS Yoneda, CQG 17 (2000) 4799

Adjusted dynamical equations:

$$\partial_t \tilde{E}^i_a = -i\mathcal{D}_j(\epsilon^{cb}{}_a \underset{\sim}{N} \tilde{E}^j_c \tilde{E}^i_b) + 2\mathcal{D}_j(N^{[j}\tilde{E}^{i]}_a) + i\mathcal{A}^b_0 \epsilon_{ab}{}^c \tilde{E}^i_c \underbrace{+ X^i_a \mathcal{C}_H + Y^{ij}_a \mathcal{C}_{Mj} + P^{ib}_a \mathcal{C}_{Gb}}_{adjust}$$

$$\partial_t \mathcal{A}^a_i = -i\epsilon^{ab}{}_c \underset{\sim}{N} \tilde{E}^j_b F^c_{ij} + N^j F^a_{ji} + \mathcal{D}_i \mathcal{A}^a_0 + \Lambda \underset{\sim}{N} \tilde{E}^a_i \underbrace{+ Q^a_i \mathcal{C}_H + R^{aj}_i \mathcal{C}_{Mj} + Z^{ab}_i \mathcal{C}_{Gb}}_{adjust}$$

Adjusted and linearized:

$$X = Y = Z = 0,\ P^{ia}_b = \kappa_1(iN^i\delta^a_b),\ Q^a_i = \kappa_2(e^{-2}\underset{\sim}{N}\tilde{E}^a_i),\ R^{aj}{}_i = \kappa_3(-ie^{-2}\underset{\sim}{N}\epsilon^{ac}{}_d \tilde{E}^d_i \tilde{E}^j_c)$$

Fourier transform and extract 0th order of the characteristic matrix:

$$\partial_t \begin{pmatrix} \hat{\mathcal{C}}_H \\ \hat{\mathcal{C}}_{Mi} \\ \hat{\mathcal{C}}_{Ga} \end{pmatrix} = \begin{pmatrix} 0 & i(1+2\kappa_3)k_j & 0 \\ i(1-2\kappa_2)k_i & \kappa_3 \epsilon^{kj}{}_i k_k & 0 \\ 0 & 2\kappa_3 \delta^j_a & 0 \end{pmatrix} \begin{pmatrix} \hat{\mathcal{C}}_H \\ \hat{\mathcal{C}}_{Mj} \\ \hat{\mathcal{C}}_{Gb} \end{pmatrix}$$

Eigenvalues:

$$\left(0, 0, 0, \pm\kappa_3\sqrt{-kx^2 - ky^2 - kz^2}, \pm\sqrt{(-1+2\kappa_2)(1+2\kappa_3)(kx^2+ky^2+kz^2)}\right)$$

In order to obtain non-positive real eigenvalues:

$$(-1+2\kappa_2)(1+2\kappa_3) < 0$$

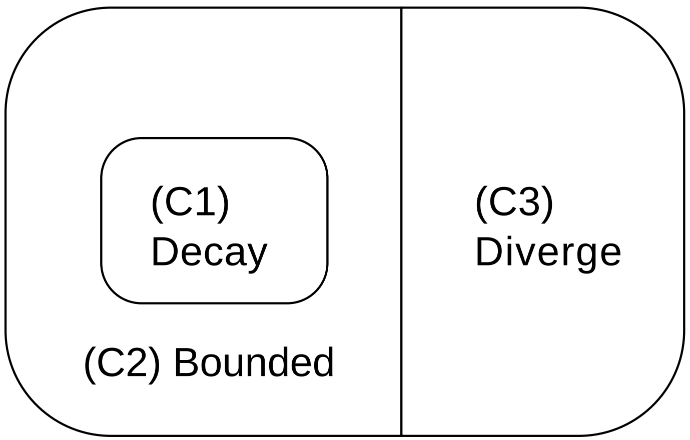
A Classification of Constraint Propagations

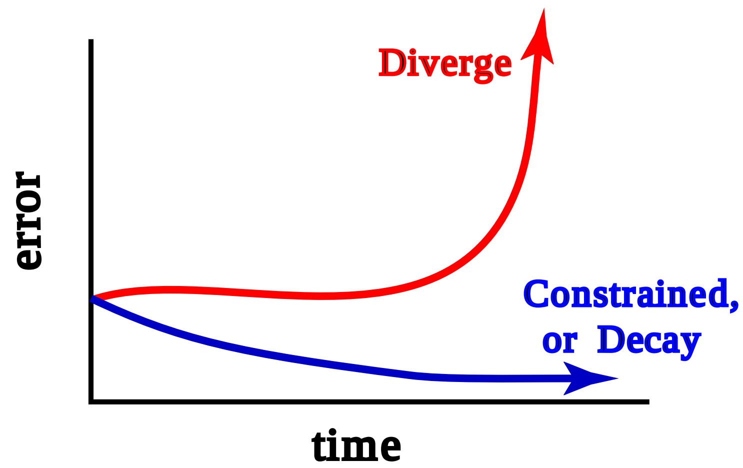
(C1) **Asymptotically constrained :**
Violation of constraints decays (converges to zero).

(C2) **Asymptotically bounded :**
Violation of constraints is bounded at a certain value.

(C3) **Diverge :**
At least one constraint will diverge.

Note that (C1) $\subset$ (C2).





A Classification of Constraint Propagations (cont.)

gr-qc/0209106

(C1) Asymptotically constrained :

Violation of constraints decays (converges to zero).

$\Leftrightarrow$ All the real parts of CAFs are negative.

(C2) Asymptotically bounded :

Violation of constraints is bounded at a certain value.

$\Leftrightarrow$

(a) All the real parts of CAFs are not positive, and

(b1) the CP matrix $M^\alpha{}_\beta$ is diagonalizable, or

(b2) the real part of the degenerated CAFs is not zero.

(C3) Diverge :

At least one constraint will diverge.

The necessary and sufficient conditions for (C1) and (C2)?

Preparation

Without loss of generality, the CP matrix M can be assumed to be a triangular matrix. Suppose we have an expression,

$$\partial_t \begin{pmatrix} C_n \\ \vdots \\ C_1 \end{pmatrix} = \begin{pmatrix} \lambda_n & * & * \\ 0 & \ddots & * \\ 0 & 0 & \lambda_1 \end{pmatrix} \begin{pmatrix} C_n \\ \vdots \\ C_1 \end{pmatrix}, \tag{1}$$

where λs are the eigenvalues of M, and the indices are formally labeled in this order.

Proposition 1 **The solution of (1) can be expressed formally as**

$$C_j(t) = \sum_{i=1}^{j} \left\{ \exp(\lambda_i t) \sum_{k=0}^{n_i-1} (a_k^{(i)} t^k) \right\}, \tag{2}$$

where λ_i is the i-th eigenvalue of M, and n_i is the multiplicity of λ_i up to $i \le j$.

Proposition 1 **The solution of (1) can be expressed formally as**

$$C_j(t) = \sum_{i=1}^{j} \left\{ \exp(\lambda_i t) \sum_{k=0}^{n_i - 1} (a_k^{(i)} t^k) \right\}, \tag{2}$$

where λ_i is the i-th eigenvalue of M, and n_i is the multiplicity of λ_i up to $i \leq j$.

For example: $\lambda_1 < \lambda_2 = \lambda_3 = \lambda_4 < \lambda_5 = \lambda_6 < \cdots$,

$$\begin{aligned}
C_1 &= \exp(\lambda_1 t)(@) \\
C_2 &= \exp(\lambda_1 t)(@) + \exp(\lambda_2 t)(@) \\
C_3 &= \exp(\lambda_1 t)(@) + \exp(\lambda_2 t)(@ + @t) \\
C_4 &= \exp(\lambda_1 t)(@) + \exp(\lambda_2 t)(@ + @t + @t^2) \\
C_5 &= \exp(\lambda_1 t)(@) + \exp(\lambda_2 t)(@ + @t + @t^2) + \exp(\lambda_5 t)(@) \\
C_6 &= \exp(\lambda_1 t)(@) + \exp(\lambda_2 t)(@ + @t + @t^2) + \exp(\lambda_5 t)(@ + @t)
\end{aligned}$$

The highest power N in all constraints is bounded by

$$N \leq \max_{1 \leq i \leq n} (\textbf{multiplicity of } \lambda_i) - 1. \tag{3}$$

Asymptotically Constrained CP – (C1) –

Theorem 1

Asymptotically constrained evolution (violation of constraints converges to zero)

$\Leftrightarrow$ **All the real parts of CAFs are negative.**

proof of $\Leftarrow$)

We use the expression (2). If $\Re e(\lambda_i) < 0$ for $\forall i$, then C will converge to zero at $t \to \infty$ no matter what $t-$polynomial terms are.

proof of $\Rightarrow$)

We show the contrapositive. Suppose there exists an eigenvalue λ_1 such as which real-part is non-negative. By setting λ_1 at the lower-end of the triangular matrix M in (1), then we get $\partial_t C_1 = \lambda_1 C_1$ which solution is $C_1 = C_1(0)\exp(\lambda_1 t)$. C_1 does not converge to zero.

Asymptotically Bounded CP – (C2) –

Theorem 2

Asymptotically bounded evolution (all the constraints are bounded at a certain value) $\Leftrightarrow$

(a) All the real parts of CAFs are not positive, and

(b1) the CP matrix $M^\alpha{}_\beta$ is diagonalizable, or

(b2) the real part of the degenerated CAFs is not zero.

proof of $\Leftarrow$ for the case (a+b1): By a diagonalization, we obtain $\partial_t C_i = \lambda_i C_i$, which solution is $C_i = C_i(0)\exp(\lambda_i t)$. This is bounded since $\Re e(\lambda_i) \le 0$.

proof of $\Leftarrow$ for the case (a+b2): We use the expression (2). When λ is degenerated, the t-polynomials have non-zero power. However, the assumption, $\Re e(\lambda) < 0$, indicates $\exp(\lambda t)$(t-polynomials) will converge to zero. When λ is not degenerated, there is only a constant term rather than t-polynomials. So that (2) remains finite for $\Re e(\lambda) \le 0$.

proof of $\Rightarrow$) We show the contrapositive.

$\overline{\textbf{(a) and \{ (b1) or (b2) \}}} \Leftrightarrow \overline{\textbf{(a)}}$ **or** $\{$**(a) and**$\{\overline{\textbf{(b1)}}$ **and** $\overline{\textbf{(b2)}}\}\}$

$\overline{\textbf{(a)}} \Rightarrow$ **diverge :: trivial.**

(a) and$\{\overline{\textbf{(b1)}}$ **and** $\overline{\textbf{(b2)}}\} \Rightarrow$ **diverge ::**

By triangulating the matrix, we can set the degenerated CAFs λ which real-part is zero. Let us consider $n = 3$ case,

$$M = \begin{pmatrix} \lambda_i & a & b \\ 0 & \lambda & c \\ 0 & 0 & \lambda \end{pmatrix}, \qquad a, b, c = \text{constant}.$$

Then we get first $C_1 = C_1(0)\exp(\lambda t)$ which is a constant or a trigonal function, and

$$\begin{aligned} \partial_t C_2 &= \lambda\, C_2 + c\, C_1 = \lambda\, C_2 + c\, C_1(0)\exp(\lambda\, t) \\ \Rightarrow \qquad C_2 &= C_2(0)\exp(\lambda\, t) + c\; C_1(0)\exp(\lambda\, t)t. \end{aligned}$$

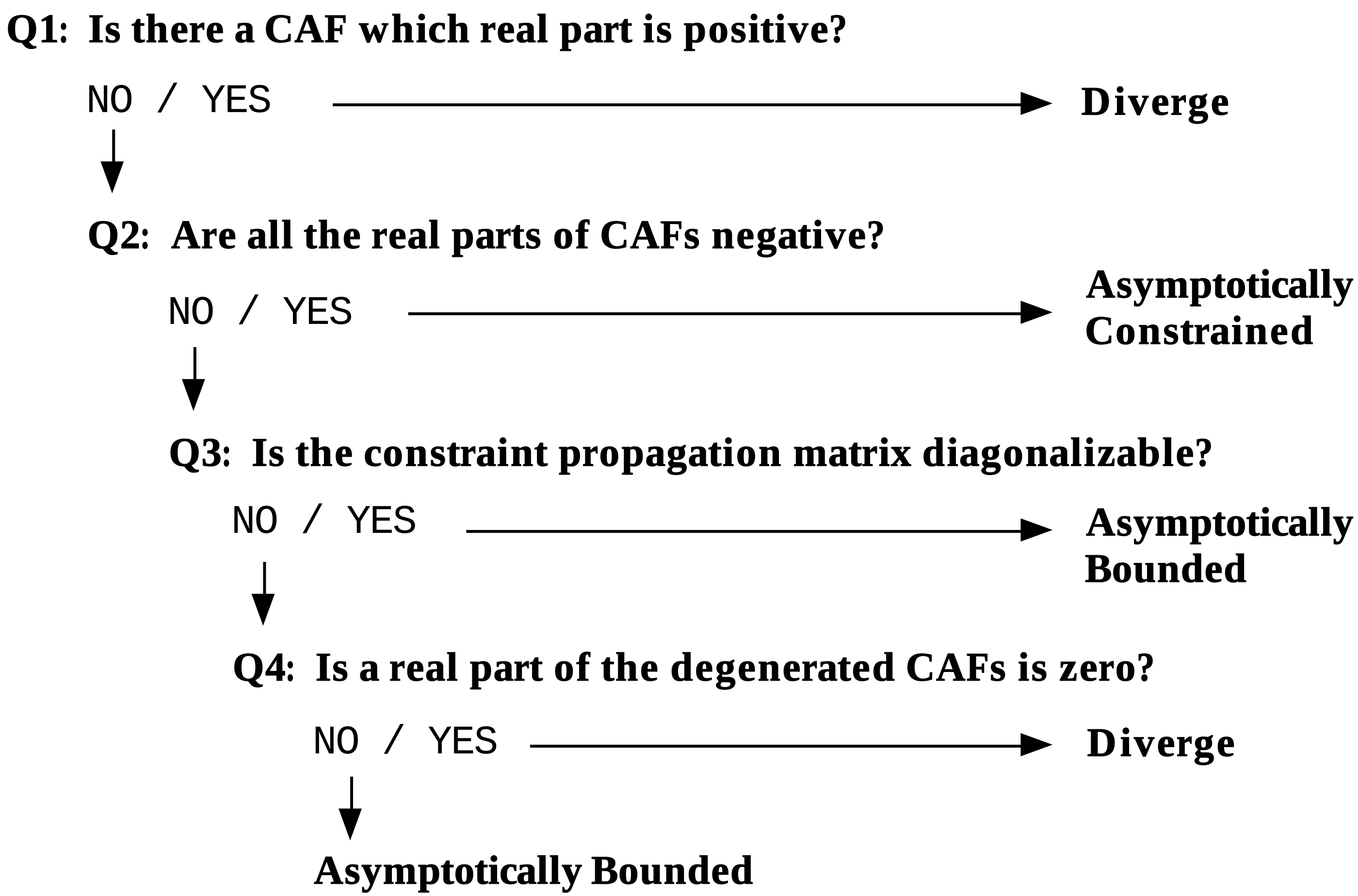
Therefore C_2 will diverge when $c \neq 0$, and remain finite when $c = 0$.

Since we are assuming the matrix is not diagonalizable, the minimal polynomial does not take the form as the product of $(M - \lambda_i E)$ for different eigenvalues λ_i. When there exists $\lambda_i \neq \lambda$, we see that

$$(M - \lambda E)(M - \lambda_i E) = \begin{pmatrix} \lambda_i - \lambda & a & b \\ 0 & 0 & c \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & a & b \\ 0 & \lambda - \lambda_i & c \\ 0 & 0 & \lambda - \lambda_i \end{pmatrix} = \begin{pmatrix} 0 & 0 & a\,c \\ 0 & 0 & c(\lambda - \lambda_i) \\ 0 & 0 & 0 \end{pmatrix},$$

which should not equal to zero matrix, that indicates $c \neq 0$. Therefore C_2 will diverge. When $\lambda = \lambda_i$, some of a, b, c is non-zero in order not to vanish $(M - \lambda E)$. Therefore related C_i will diverge.

A flowchart to classify the fate of constraint propagation.



Constructing Asymptotically Constrained Systems

Hisaaki Shinkai

1. Introduction

2. Three approaches
   (1) Arnowitt-Deser-Misner / Baumgarte-Shapiro-Shibata-Nakamura
   (2) Hyperbolic formulations
   (3) Attractor systems – "Adjusted Systems"

3. Adjusted ADM systems

4. Adjusted BSSN systems

5. Summary

3 Adjusted ADM systems

We adjust the standard ADM system using constraints as:

$$\partial_t \gamma_{ij} = -2\alpha K_{ij} + \nabla_i \beta_j + \nabla_j \beta_i, \tag{1}$$

$$+P_{ij}\mathcal{H} + Q^k{}_{ij}\mathcal{M}_k + p^k{}_{ij}(\nabla_k \mathcal{H}) + q^{kl}{}_{ij}(\nabla_k \mathcal{M}_l), \tag{2}$$

$$\partial_t K_{ij} = \alpha R^{(3)}_{ij} + \alpha K K_{ij} - 2\alpha K_{ik}K^k{}_j - \nabla_i \nabla_j \alpha + (\nabla_i \beta^k) K_{kj} + (\nabla_j \beta^k) K_{ki} + \beta^k \nabla_k K_{ij}, \tag{3}$$

$$+R_{ij}\mathcal{H} + S^k{}_{ij}\mathcal{M}_k + r^k{}_{ij}(\nabla_k \mathcal{H}) + s^{kl}{}_{ij}(\nabla_k \mathcal{M}_l), \tag{4}$$

with constraint equations

$$\mathcal{H} := R^{(3)} + K^2 - K_{ij}K^{ij}, \tag{5}$$

$$\mathcal{M}_i := \nabla_j K^j{}_i - \nabla_i K. \tag{6}$$

We can write the adjusted constraint propagation equations as

$$\partial_t \mathcal{H} = \text{(original terms)} + H_1^{mn}[(2)] + H_2^{imn}\partial_i[(2)] + H_3^{ijmn}\partial_i\partial_j[(2)] + H_4^{mn}[(4)], \tag{7}$$

$$\partial_t \mathcal{M}_i = \text{(original terms)} + M_{1i}{}^{mn}[(2)] + M_{2i}{}^{jmn}\partial_j[(2)] + M_{3i}{}^{mn}[(4)] + M_{4i}{}^{jmn}\partial_j[(4)]. \tag{8}$$

Original ADM The original construction by ADM uses the pair of (h_{ij}, π^{ij}).

$$\mathcal{L} = \sqrt{-g}R = \sqrt{h}N[{}^{(3)}R - K^2 + K_{ij}K^{ij}], \quad \text{where } K_{ij} = \frac{1}{2}\pounds_n h_{ij}$$

$$\text{then} \quad \pi^{ij} = \frac{\partial \mathcal{L}}{\partial \dot{h}_{ij}} = \sqrt{h}(K^{ij} - Kh^{ij}),$$

The Hamiltonian density gives us constraints and evolution eqs.

$$\mathcal{H} = \pi^{ij}\dot{h}_{ij} - \mathcal{L} = \sqrt{h}\left\{N\mathcal{H}(h,\pi) - 2N_j\mathcal{M}^j(h,\pi) + 2D_i(h^{-1/2}N_j\pi^{ij})\right\},$$

$$\begin{cases} \partial_t h_{ij} = \dfrac{\delta \mathcal{H}}{\delta \pi^{ij}} = 2\dfrac{N}{\sqrt{h}}(\pi_{ij} - \dfrac{1}{2}h_{ij}\pi) + 2D_{(i}N_{j)}, \\ \partial_t \pi^{ij} = -\dfrac{\delta \mathcal{H}}{\delta h_{ij}} = -\sqrt{h}N({}^{(3)}R^{ij} - \dfrac{1}{2}{}^{(3)}Rh^{ij}) + \dfrac{1}{2}\dfrac{N}{\sqrt{h}}h^{ij}(\pi_{mn}\pi^{mn} - \dfrac{1}{2}\pi^2) - 2\dfrac{N}{\sqrt{h}}(\pi^{in}\pi_n{}^j - \dfrac{1}{2}\pi\pi^{ij}) \\ \qquad + \sqrt{h}(D^iD^jN - h^{ij}D^mD_mN) + \sqrt{h}D_m(h^{-1/2}N^m\pi^{ij}) - 2\pi^{m(i}D_mN^{j)} \end{cases}$$

Standard ADM (by York) NRists refer ADM as the one by York with a pair of (h_{ij}, K_{ij}).

$$\begin{cases} \partial_t h_{ij} = -2NK_{ij} + D_jN_i + D_iN_j, \\ \partial_t K_{ij} = N({}^{(3)}R_{ij} + KK_{ij}) - 2NK_{il}K^l{}_j - D_iD_jN + (D_jN^m)K_{mi} + (D_iN^m)K_{mj} + N^mD_mK_{ij} \end{cases}$$

In the process of converting, $\mathcal{H}$ was used, i.e. the standard ADM has already adjusted.

3 Constraint propagation of ADM systems

3.1 Original ADM vs Standard ADM

Try the adjustment $\underline{R_{ij} = \kappa_1 \alpha \gamma_{ij}}$ and other multiplier zero, where $\kappa_1 = \begin{cases} 0 & \text{the standard ADM} \\ -1/4 & \text{the original ADM} \end{cases}$

- The constraint propagation eqs keep the first-order form (cf Frittelli, PRD55(97)5992):

$$\partial_t \begin{pmatrix} \mathcal{H} \\ \mathcal{M}_i \end{pmatrix} \simeq \begin{pmatrix} \beta^l & -2\alpha\gamma^{jl} \\ -(1/2)\alpha\delta^l_i + R^l{}_i - \delta^l_i R & \beta^l \delta^j_i \end{pmatrix} \partial_l \begin{pmatrix} \mathcal{H} \\ \mathcal{M}_j \end{pmatrix}. \quad (5)$$

The eigenvalues of the characteristic matrix:

$$\lambda^l = (\beta^l, \beta^l, \beta^l \pm \sqrt{\alpha^2 \gamma^{ll}(1+4\kappa_1)})$$

The hyperbolicity of (5): $\begin{cases} \text{symmetric hyperbolic} & \text{when } \kappa_1 = 3/2 \\ \text{strongly hyperbolic} & \text{when } \alpha^2\gamma^{ll}(1+4\kappa_1) > 0 \\ \text{weakly hyperbolic} & \text{when } \alpha^2\gamma^{ll}(1+4\kappa_1) \geq 0 \end{cases}$

- On the Minkowskii background metric, the linear order terms of the Fourier-transformed constraint propagation equations gives the eigenvalues

$$\Lambda^l = (0, 0, \pm\sqrt{-k^2(1+4\kappa_1)}).$$

That is, $\begin{cases} \text{(two 0s, two pure imaginary)} & \text{for the standard ADM} \\ \text{(four 0s)} & \text{for the original ADM} \end{cases}$ BETTER STABILITY

4 Constraint propagations in spherically symmetric spacetime

4.1 The procedure

The discussion becomes clear if we expand the constraint $C_\mu := (\mathcal{H}, \mathcal{M}_i)^T$ using vector harmonics.

$$C_\mu = \sum_{l,m} \left(A^{lm}(t,r) a_{lm}(\theta,\varphi) + B^{lm} b_{lm} + C^{lm} c_{lm} + D^{lm} d_{lm} \right), \qquad (1)$$

where we choose the basis of the vector harmonics as

$$a_{lm} = \begin{pmatrix} Y_{lm} \\ 0 \\ 0 \\ 0 \end{pmatrix}, b_{lm} = \begin{pmatrix} 0 \\ Y_{lm} \\ 0 \\ 0 \end{pmatrix}, c_{lm} = \frac{r}{\sqrt{l(l+1)}} \begin{pmatrix} 0 \\ 0 \\ \partial_\theta Y_{lm} \\ \partial_\varphi Y_{lm} \end{pmatrix}, d_{lm} = \frac{r}{\sqrt{l(l+1)}} \begin{pmatrix} 0 \\ 0 \\ -\frac{1}{\sin\theta}\partial_\varphi Y_{lm} \\ \sin\theta\, \partial_\theta Y_{lm} \end{pmatrix}.$$

The basis are normalized so that they satisfy

$$\langle C_\mu, C_\nu \rangle = \int_0^{2\pi} d\varphi \int_0^{\pi} C_\mu^* C_\rho \, \eta^{\nu\rho} \sin\theta d\theta,$$

where $\eta^{\nu\rho}$ is Minkowskii metric and the asterisk denotes the complex conjugate. Therefore

$$A^{lm} = \langle a^{lm}_{(\nu)}, C_\nu \rangle, \quad \partial_t A^{lm} = \langle a^{lm}_{(\nu)}, \partial_t C_\nu \rangle, \quad \text{etc.}$$

We also express these evolution equations using the Fourier expansion on the radial coordinate,

$$A^{lm} = \sum_k \hat{A}^{lm}_{(k)}(t)\, e^{ikr} \quad \text{etc.} \qquad (2)$$

So that we will be able to obtain the RHS of the evolution equations for $(\hat{A}^{lm}_{(k)}(t), \cdots, \hat{D}^{lm}_{(k)}(t))^T$ in a homogeneous form.

Example 1: standard ADM vs original ADM (in Schwarzschild coordinate)

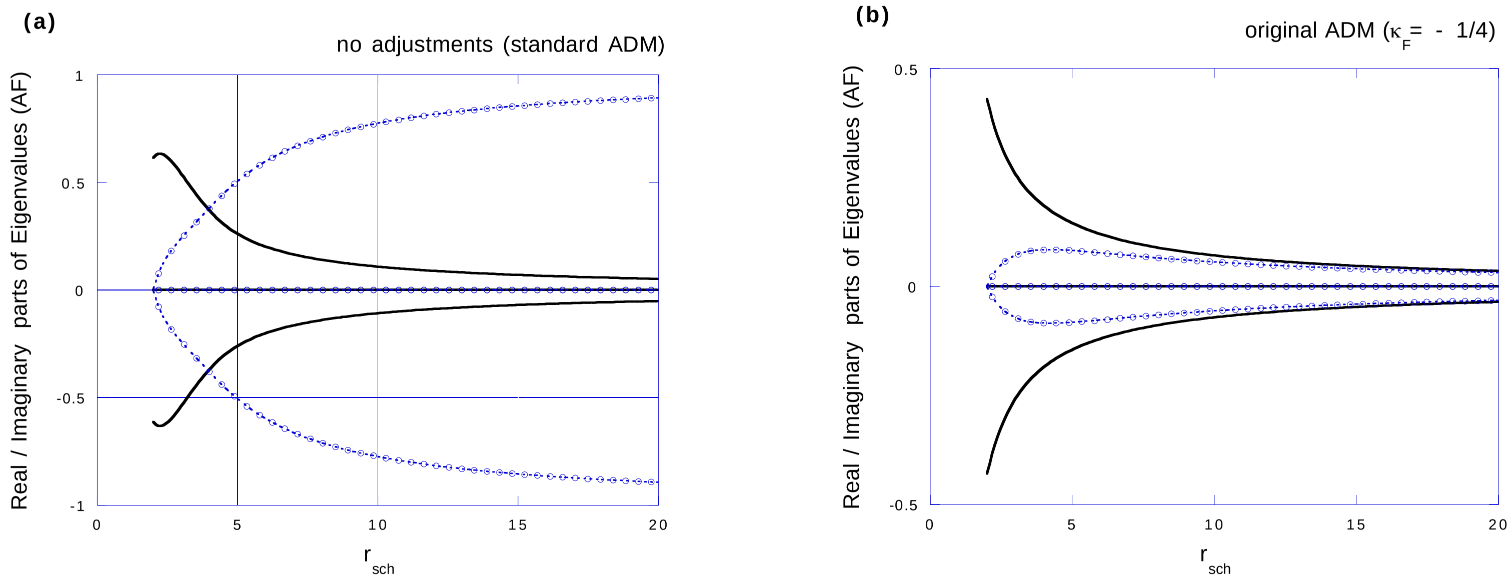


Figure 1: Amplification factors (AFs, eigenvalues of homogenized constraint propagation equations) are shown for the standard Schwarzschild coordinate, with (a) no adjustments, i.e., standard ADM, (b) original ADM ($\kappa_F = -1/4$). The solid lines and the dotted lines with circles are real parts and imaginary parts, respectively. They are four lines each, but actually the two eigenvalues are zero for all cases. Plotting range is $2 < r \leq 20$ using Schwarzschild radial coordinate. We set $k = 1, l = 2$, and $m = 2$ throughout the article.

$$\begin{aligned}
\partial_t \gamma_{ij} &= -2\alpha K_{ij} + \nabla_i \beta_j + \nabla_j \beta_i, \\
\partial_t K_{ij} &= \alpha R^{(3)}_{ij} + \alpha K K_{ij} - 2\alpha K_{ik} K^k{}_j - \nabla_i \nabla_j \alpha + (\nabla_i \beta^k) K_{kj} + (\nabla_j \beta^k) K_{ki} + \beta^k \nabla_k K_{ij} + \kappa_F \alpha \gamma_{ij} \mathcal{H},
\end{aligned}$$

Example 2: Detweiler-type adjusted (in Schwarzschild coord.)

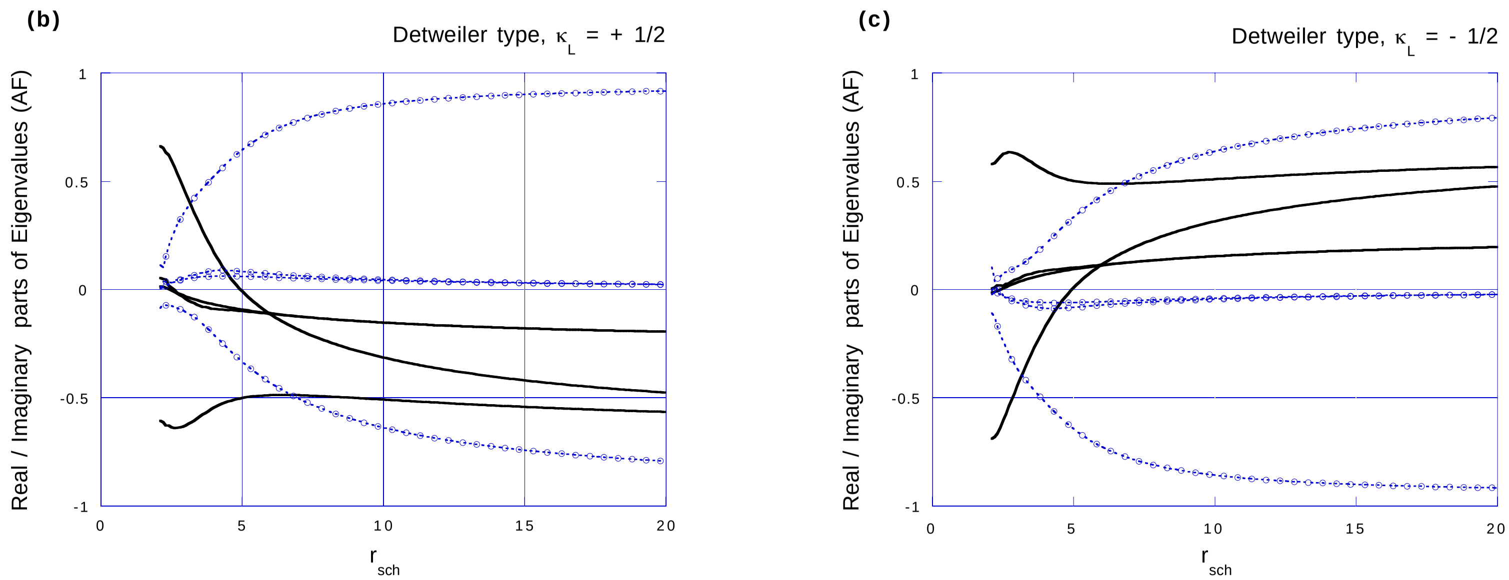


Figure 2: Amplification factors of the standard Schwarzschild coordinate, with Detweiler type adjustments. Multipliers used in the plot are (b) $\kappa_L = +1/2$, and (c) $\kappa_L = -1/2$.

$$\partial_t \gamma_{ij} = \text{(original terms)} + P_{ij}\mathcal{H},$$

$$\partial_t K_{ij} = \text{(original terms)} + R_{ij}\mathcal{H} + S^k{}_{ij}\mathcal{M}_k + s^{kl}{}_{ij}(\nabla_k \mathcal{M}_l),$$

where $P_{ij} = -\kappa_L \alpha^3 \gamma_{ij}, \quad R_{ij} = \kappa_L \alpha^3 (K_{ij} - (1/3)K\gamma_{ij}),$

$$S^k{}_{ij} = \kappa_L \alpha^2 [3(\partial_{(i}\alpha)\delta^k_{j)} - (\partial_l \alpha)\gamma_{ij}\gamma^{kl}], \quad s^{kl}{}_{ij} = \kappa_L \alpha^3 [\delta^k_{(i}\delta^l_{j)} - (1/3)\gamma_{ij}\gamma^{kl}],$$

Example 3: standard ADM (in isotropic/iEF coord.)

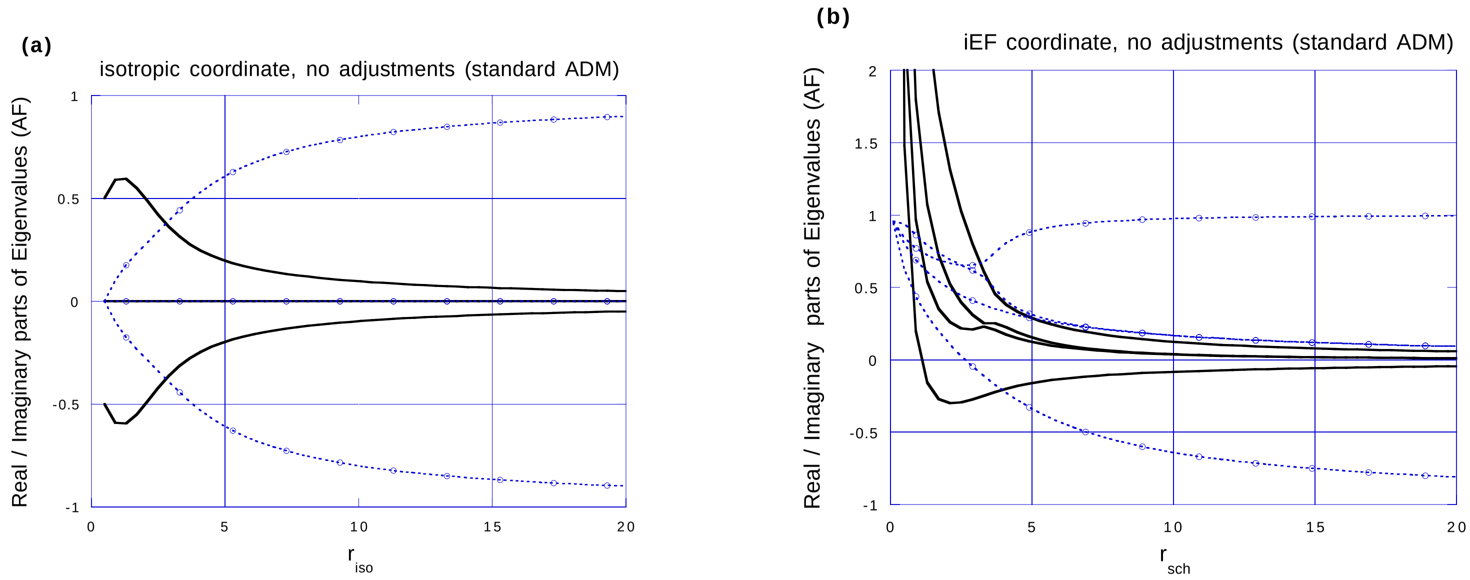


Figure 3: Comparison of amplification factors between different coordinate expressions for the standard ADM formulation (i.e. no adjustments). Fig. (a) is for the isotropic coordinate (1), and the plotting range is $1/2 \le r_{iso}$. Fig. (b) is for the iEF coordinate (1) and we plot lines on the $t = 0$ slice for each expression. The solid four lines and the dotted four lines with circles are real parts and imaginary parts, respectively.

Example 4: Detweiler-type adjusted (in iEF/PG coord.)

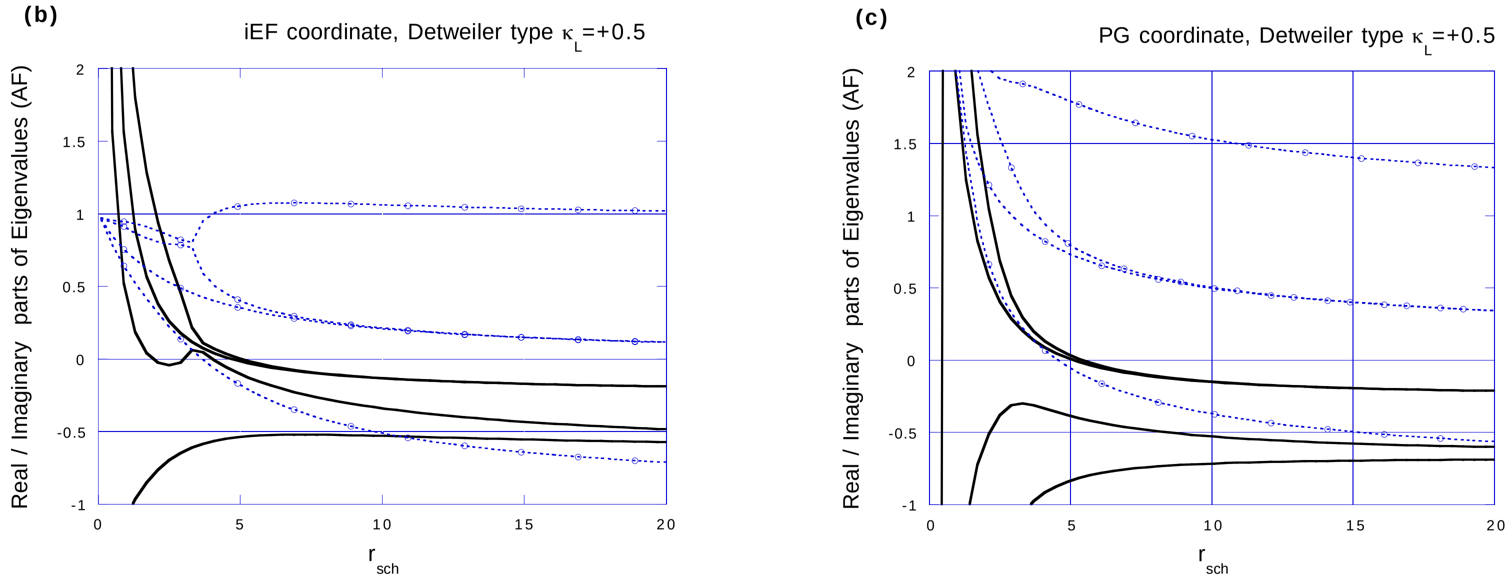


Figure 4: Similar comparison for Detweiler adjustments. $\kappa_L = +1/2$ for all plots.

No.	No. in Table.??	adjustment		1st?	Sch/iso coords.			iEF/PG coords.	
					TRS	real.	imag.	real.	imag.
0	0	–	no adjustments	yes	–	–	–	–	–
P-1	2-P	P_{ij}	$-\kappa_L \alpha^3 \gamma_{ij}$	no	no	makes 2 Neg.	not apparent	makes 2 Neg.	not apparent
P-2	3	P_{ij}	$-\kappa_L \alpha \gamma_{ij}$	no	no	makes 2 Neg.	not apparent	makes 2 Neg.	not apparent
P-3	-	P_{ij}	$P_{rr} = -\kappa$ or $P_{rr} = -\kappa\alpha$	no	no	slightly enl.Neg.	not apparent	slightly enl.Neg.	not apparent
P-4	-	P_{ij}	$-\kappa \gamma_{ij}$	no	no	makes 2 Neg.	not apparent	makes 2 Neg.	not apparent
P-5	-	P_{ij}	$-\kappa \gamma_{rr}$	no	no	red. Pos./enl.Neg.	not apparent	red.Pos./enl.Neg.	not apparent
Q-1	-	$Q^k{}_{ij}$	$\kappa\alpha\beta^k\gamma_{ij}$	no	no	N/A	N/A	$\kappa \sim 1.35$ min. vals.	not apparent
Q-2	-	$Q^k{}_{ij}$	$Q^r{}_{rr} = \kappa$	no	yes	red. abs vals.	not apparent	red. abs vals.	not apparent
Q-3	-	$Q^k{}_{ij}$	$Q^r{}_{ij} = \kappa\gamma_{ij}$ or $Q^r{}_{ij} = \kappa\alpha\gamma_{ij}$	no	yes	red. abs vals.	not apparent	enl.Neg.	enl. vals.
Q-4	-	$Q^k{}_{ij}$	$Q^r{}_{rr} = \kappa\gamma_{rr}$	no	yes	red. abs vals.	not apparent	red. abs vals.	not apparent
R-1	1	R_{ij}	$\kappa_F \alpha \gamma_{ij}$	yes	yes	$\kappa_F = -1/4$ min. abs vals.		$\kappa_F = -1/4$ min. vals.	
R-2	4	R_{ij}	$R_{rr} = -\kappa_\mu \alpha$ or $R_{rr} = -\kappa_\mu$	yes	no	not apparent	not apparent	red.Pos./enl.Neg.	enl. vals.
R-3	-	R_{ij}	$R_{rr} = -\kappa\gamma_{rr}$	yes	no	enl. vals.	not apparent	red.Pos./enl.Neg.	enl. vals.
S-1	2-S	$S^k{}_{ij}$	$\kappa_L\alpha^2[3(\partial_{(i}\alpha)\delta^k_{j)} - (\partial_l\alpha)\gamma_{ij}\gamma^{kl}]$	yes	no	not apparent	not apparent	not apparent	not apparent
S-2	-	$S^k{}_{ij}$	$\kappa\alpha\gamma^{lk}(\partial_l\gamma_{ij})$	yes	no	makes 2 Neg.	not apparent	makes 2 Neg.	not apparent
p-1	-	$p^k{}_{ij}$	$p^r{}_{ij} = -\kappa\alpha\gamma_{ij}$	no	no	red. Pos.	red. vals.	red. Pos.	enl. vals.
p-2	-	$p^k{}_{ij}$	$p^r{}_{rr} = \kappa\alpha$	no	no	red. Pos.	red. vals.	red.Pos/enl.Neg.	enl. vals.
p-3	-	$p^k{}_{ij}$	$p^r{}_{rr} = \kappa\alpha\gamma_{rr}$	no	no	makes 2 Neg.	enl. vals.	red. Pos. vals.	red. vals.
q-1	-	$q^{kl}{}_{ij}$	$q^{rr}{}_{ij} = \kappa\alpha\gamma_{ij}$	no	no	$\kappa = 1/2$ min. vals.	red. vals.	not apparent	enl. vals.
q-2	-	$q^{kl}{}_{ij}$	$q^{rr}{}_{rr} = -\kappa\alpha\gamma_{rr}$	no	yes	red. abs vals.	not apparent	not apparent	not apparent
r-1	-	$r^k{}_{ij}$	$r^r{}_{ij} = \kappa\alpha\gamma_{ij}$	no	yes	not apparent	not apparent	not apparent	enl. vals.
r-2	-	$r^k{}_{ij}$	$r^r{}_{rr} = -\kappa\alpha$	no	yes	red. abs vals.	enl. vals.	red. abs vals.	enl. vals.
r-3	-	$r^k{}_{ij}$	$r^r{}_{rr} = -\kappa\alpha\gamma_{rr}$	no	yes	red. abs vals.	enl. vals.	red. abs vals.	enl. vals.
s-1	2-s	$s^{kl}{}_{ij}$	$\kappa_L\alpha^3[\delta^k_{(i}\delta^l_{j)} - (1/3)\gamma_{ij}\gamma^{kl}]$	no	no	makes 4 Neg.	not apparent	makes 4 Neg.	not apparent
s-2	-	$s^{kl}{}_{ij}$	$s^{rr}{}_{ij} = -\kappa\alpha\gamma_{ij}$	no	no	makes 2 Neg.	red. vals.	makes 2 Neg.	red. vals.
s-3	-	$s^{kl}{}_{ij}$	$s^{rr}{}_{rr} = -\kappa\alpha\gamma_{rr}$	no	no	makes 2 Neg.	red. vals.	makes 2 Neg.	red. vals.

Table 1: List of adjustments we tested in the Schwarzschild spacetime. The column of adjustments are nonzero multipliers. The effects to amplification factors (when $\kappa > 0$) are commented for each coordinate system and for real/imaginary parts of AFs, respectively. The 'N/A' means that there is no effect due to the coordinate properties; 'not apparent' means the adjustment does not change the AFs effectively according to our conjecture; 'enl./red./min.' means enlarge/reduce/minimize, and 'Pos./Neg.' means positive/negative, respectively. These judgements are made at the $r \sim O(10M)$ region on their $t = 0$ slice.

3.2.2 Numerical demonstration

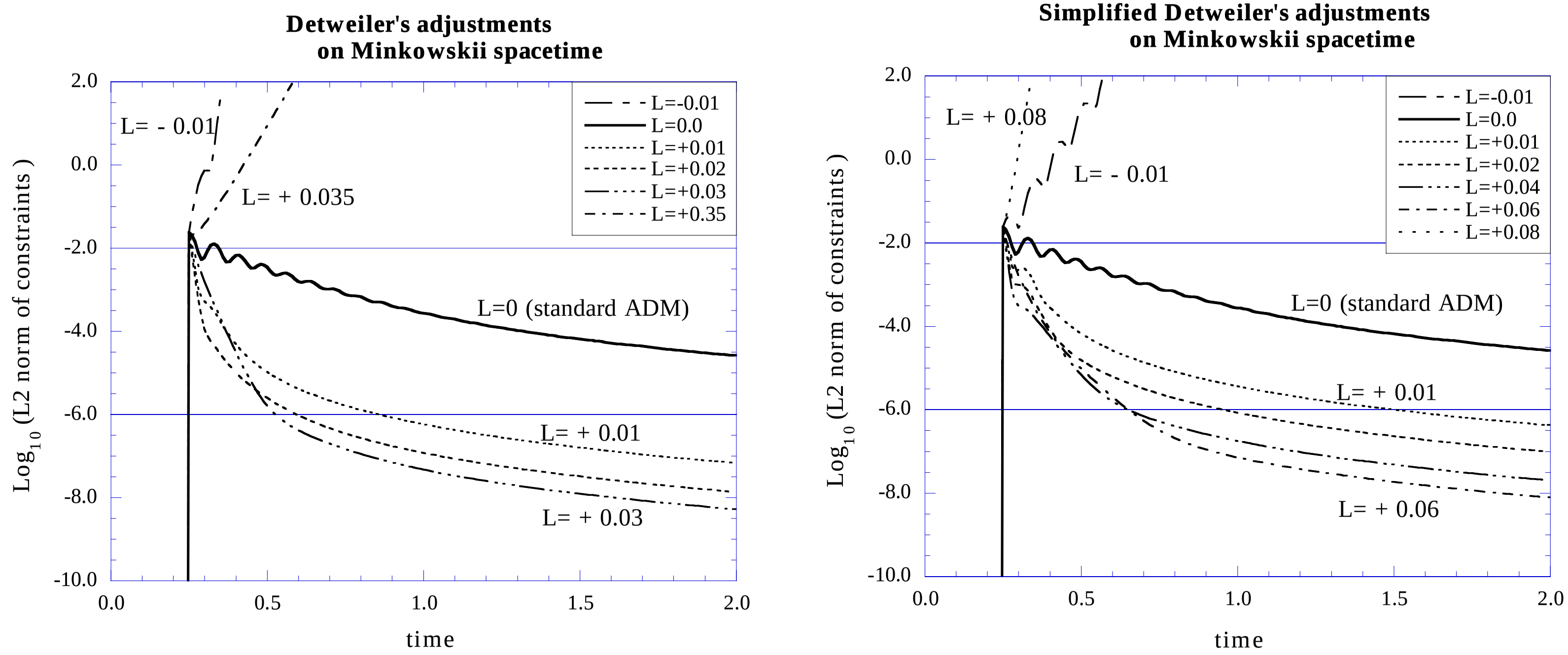


Figure 1: We confirmed numerically, using Minkowskii perturbation, that Detweiler's system presents better accuracy than the standard ADM, but only form small positive L.

Comparisons of Adjusted ADM systems (linear wave)

Mexico NR 2002 Workshop participants

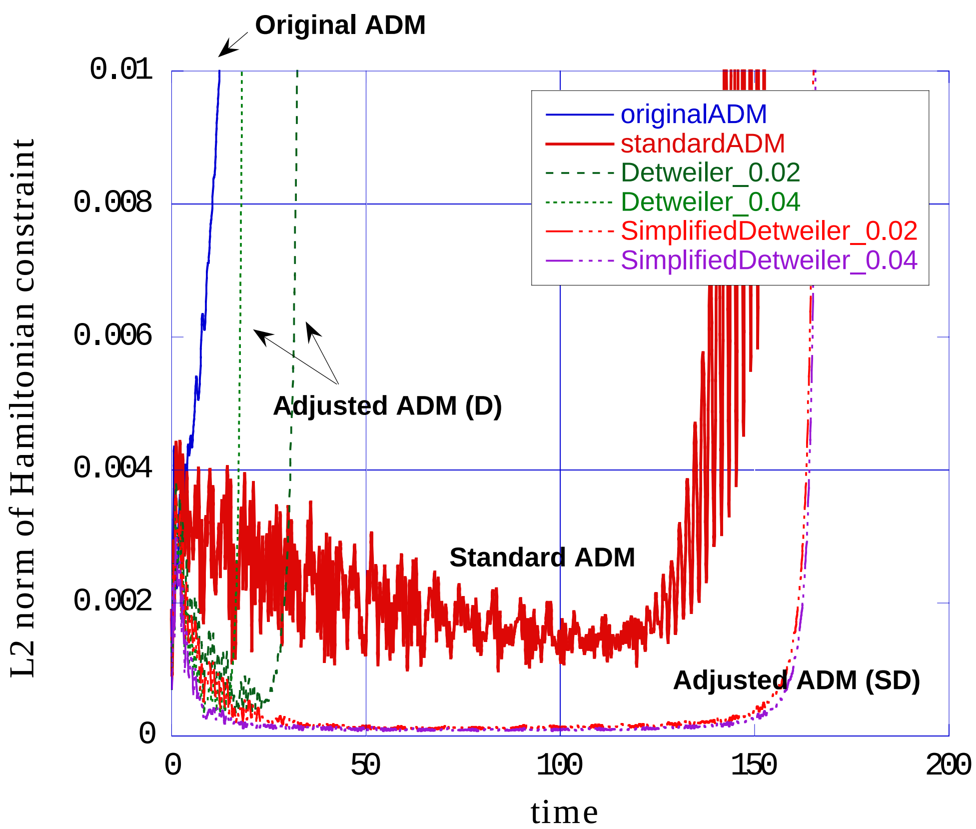


Figure 1: Violation of Hamiltonian constraints versus time: Adjusted ADM systems applied for Teukolsky wave initial data evolution with harmonic slicing, and with periodic boundary condition. Cactus/CactusEinstein/ADM code was used. Grid = 24^3, $\Delta x = 0.25$, iterative Crank-Nicholson method.

"Einstein equations" are time-reversal invariant. So ...

Why all negative amplification factors (AFs) are available?

Explanation by the time-reversal invariance (TRI)

- the adjustment of the system I,

$$\text{adjust term to } \underbrace{\partial_t}_{(-)} \underbrace{K_{ij}}_{(-)} = \kappa_1 \underbrace{\alpha}_{(+)} \underbrace{\gamma_{ij}}_{(+)} \underbrace{\mathcal{H}}_{(+)}$$

preserves TRI. ... so the AFs remain zero (unchange).

- the adjustment by (a part of) Detweiler

$$\text{adjust term to } \underbrace{\partial_t}_{(-)} \underbrace{\gamma_{ij}}_{(+)} = -L \underbrace{\alpha}_{(+)} \underbrace{\gamma_{ij}}_{(+)} \underbrace{\mathcal{H}}_{(+)}$$

violates TRI. ... so the AFs can become negative.

Therefore

We can break the time-reversal invariant feature of the "ADM equations".

Constructing Asymptotically Constrained Systems

Hisaaki Shinkai

1. Introduction
2. Three approaches
   (1) Arnowitt-Deser-Misner / Baumgarte-Shapiro-Shibata-Nakamura
   (2) Hyperbolic formulations
   (3) Attractor systems – "Adjusted Systems"
3. Adjusted ADM systems
4. Adjusted BSSN systems
5. Summary

strategy 1 Shibata-Nakamura's (Baumgarte-Shapiro's) modifications to the standard ADM

– define new variables ($\phi, \tilde{\gamma}_{ij}, K, \tilde{A}_{ij}, \tilde{\Gamma}^i$), instead of the ADM's (γ_{ij}, K_{ij}) where

$$\tilde{\gamma}_{ij} \equiv e^{-4\phi}\gamma_{ij}, \qquad \tilde{A}_{ij} \equiv e^{-4\phi}(K_{ij} - (1/3)\gamma_{ij}K), \qquad \tilde{\Gamma}^i \equiv \tilde{\Gamma}^i_{jk}\tilde{\gamma}^{jk},$$

use momentum constraint in Γ^i-eq., and impose $\det\tilde{\gamma}_{ij} = 1$ during the evolutions.

– The set of evolution equations become

$$\begin{aligned}
(\partial_t - \mathcal{L}_\beta)\phi &= -(1/6)\alpha K, \\
(\partial_t - \mathcal{L}_\beta)\tilde{\gamma}_{ij} &= -2\alpha\tilde{A}_{ij}, \\
(\partial_t - \mathcal{L}_\beta)K &= \alpha\tilde{A}_{ij}\tilde{A}^{ij} + (1/3)\alpha K^2 - \gamma^{ij}(\nabla_i\nabla_j\alpha), \\
(\partial_t - \mathcal{L}_\beta)\tilde{A}_{ij} &= -e^{-4\phi}(\nabla_i\nabla_j\alpha)^{TF} + e^{-4\phi}\alpha R^{(3)}_{ij} - e^{-4\phi}\alpha(1/3)\gamma_{ij}R^{(3)} + \alpha(K\tilde{A}_{ij} - 2\tilde{A}_{ik}\tilde{A}^k{}_j) \\
\partial_t\tilde{\Gamma}^i &= -2(\partial_j\alpha)\tilde{A}^{ij} - (4/3)\alpha(\partial_j K)\tilde{\gamma}^{ij} + 12\alpha\tilde{A}^{ji}(\partial_j\phi) - 2\alpha\tilde{A}_k{}^j(\partial_j\tilde{\gamma}^{ik}) - 2\alpha\tilde{\Gamma}^k{}_{lj}\tilde{A}^j{}_k\tilde{\gamma}^{il} \\
&\quad -\partial_j\left(\beta^k\partial_k\tilde{\gamma}^{ij} - \tilde{\gamma}^{kj}(\partial_k\beta^i) - \tilde{\gamma}^{ki}(\partial_k\beta^j) + (2/3)\tilde{\gamma}^{ij}(\partial_k\beta^k)\right)
\end{aligned}$$

$$\begin{aligned}
R_{ij} &= \partial_k\Gamma^k_{ij} - \partial_i\Gamma^k_{kj} + \Gamma^m_{ij}\Gamma^k_{mk} - \Gamma^m_{kj}\Gamma^k_{mi} =: \tilde{R}_{ij} + R^\phi_{ij} \\
&\quad R^\phi_{ij} = -2\tilde{D}_i\tilde{D}_j\phi - 2\tilde{g}_{ij}\tilde{D}^l\tilde{D}_l\phi + 4(\tilde{D}_i\phi)(\tilde{D}_j\phi) - 4\tilde{g}_{ij}(\tilde{D}^l\phi)(\tilde{D}_l\phi) \\
&\quad \tilde{R}_{ij} = -(1/2)\tilde{g}^{lm}\partial_{lm}\tilde{g}_{ij} + \tilde{g}_{k(i}\partial_{j)}\tilde{\Gamma}^k + \tilde{\Gamma}^k\tilde{\Gamma}_{(ij)k} + 2\tilde{g}^{lm}\tilde{\Gamma}^k_{l(i}\tilde{\Gamma}_{j)km} + \tilde{g}lm\tilde{\Gamma}^k_{im}\tilde{\Gamma}_{klj}
\end{aligned}$$

– No explicit explanations why this formulation works better.

AEI group (2000): the replacement by momentum constraint is essential.

Constraints in BSSN system

The normal Hamiltonian and momentum constraints

$$\mathcal{H}^{BSSN} = R^{BSSN} + K^2 - K_{ij}K^{ij}, \tag{1}$$

$$\mathcal{M}_i^{BSSN} = \mathcal{M}_i^{ADM}, \tag{2}$$

Additionally, we regard the following three as the constraints:

$$\mathcal{G}^i = \tilde{\Gamma}^i - \tilde{\gamma}^{jk}\tilde{\Gamma}^i_{jk}, \tag{3}$$

$$\mathcal{A} = \tilde{A}_{ij}\tilde{\gamma}^{ij}, \tag{4}$$

$$\mathcal{S} = \tilde{\gamma} - 1, \tag{5}$$

Adjustments in evolution equations

$$\partial_t^B \varphi = \partial_t^A \varphi + (1/6)\alpha\mathcal{A} - (1/12)\tilde{\gamma}^{-1}(\partial_j\mathcal{S})\beta^j, \tag{6}$$

$$\partial_t^B \tilde{\gamma}_{ij} = \partial_t^A \tilde{\gamma}_{ij} - (2/3)\alpha\tilde{\gamma}_{ij}\mathcal{A} + (1/3)\tilde{\gamma}^{-1}(\partial_k\mathcal{S})\beta^k\tilde{\gamma}_{ij}, \tag{7}$$

$$\partial_t^B K = \partial_t^A K - (2/3)\alpha K\mathcal{A} - \alpha\mathcal{H}^{BSSN} + \alpha e^{-4\varphi}(\tilde{D}_j\mathcal{G}^j), \tag{8}$$

$$\begin{aligned}\partial_t^B \tilde{A}_{ij} = {}& \partial_t^A \tilde{A}_{ij} + ((1/3)\alpha\tilde{\gamma}_{ij}K - (2/3)\alpha\tilde{A}_{ij})\mathcal{A} + ((1/2)\alpha e^{-4\varphi}(\partial_k\tilde{\gamma}_{ij}) - (1/6)\alpha e^{-4\varphi}\tilde{\gamma}_{ij}\tilde{\gamma}^{-1}(\partial_k\mathcal{S}))\mathcal{G}^k \\ & + \alpha e^{-4\varphi}\tilde{\gamma}_{k(i}(\partial_{j)}\mathcal{G}^k) - (1/3)\alpha e^{-4\varphi}\tilde{\gamma}_{ij}(\partial_k\mathcal{G}^k)\end{aligned} \tag{9}$$

$$\begin{aligned}\partial_t^B \tilde{\Gamma}^i = {}& \partial_t^A \tilde{\Gamma}^i - ((2/3)(\partial_j\alpha)\tilde{\gamma}^{ji} + (2/3)\alpha(\partial_j\tilde{\gamma}^{ji}) + (1/3)\alpha\tilde{\gamma}^{ji}\tilde{\gamma}^{-1}(\partial_j\mathcal{S}) - 4\alpha\tilde{\gamma}^{ij}(\partial_j\varphi))\mathcal{A} - (2/3)\alpha\tilde{\gamma}^{ji}(\partial_j\mathcal{A}) \\ & + 2\alpha\tilde{\gamma}^{ij}\mathcal{M}_j - (1/2)(\partial_k\beta^i)\tilde{\gamma}^{kj}\tilde{\gamma}^{-1}(\partial_j\mathcal{S}) + (1/6)(\partial_j\beta^k)\tilde{\gamma}^{ij}\tilde{\gamma}^{-1}(\partial_k\mathcal{S}) + (1/3)(\partial_k\beta^k)\tilde{\gamma}^{ij}\tilde{\gamma}^{-1}(\partial_j\mathcal{S}) \\ & + (5/6)\beta^k\tilde{\gamma}^{-2}\tilde{\gamma}^{ij}(\partial_k\mathcal{S})(\partial_j\mathcal{S}) + (1/2)\beta^k\tilde{\gamma}^{-1}(\partial_k\tilde{\gamma}^{ij})(\partial_j\mathcal{S}) + (1/3)\beta^k\tilde{\gamma}^{-1}(\partial_j\tilde{\gamma}^{ji})(\partial_k\mathcal{S}).\end{aligned} \tag{10}$$

A Full set of BSSN constraint propagation eqs.

$$\partial_t^{BS}\begin{pmatrix}\mathcal{H}^{BS}\\ \mathcal{M}_i\\ \mathcal{G}^i\\ \mathcal{S}\\ \mathcal{A}\end{pmatrix}=\begin{pmatrix}A_{11} & A_{12} & A_{13} & A_{14} & A_{15}\\ -(1/3)(\partial_i\alpha)+(1/6)\partial_i & \alpha K & A_{23} & 0 & A_{25}\\ 0 & \alpha\tilde\gamma^{ij} & 0 & A_{34} & A_{35}\\ 0 & 0 & 0 & \beta^k(\partial_k\mathcal{S}) & -2\alpha\tilde\gamma\\ 0 & 0 & 0 & 0 & \alpha K+\beta^k\partial_k\end{pmatrix}\begin{pmatrix}\mathcal{H}^{BS}\\ \mathcal{M}_j\\ \mathcal{G}^j\\ \mathcal{S}\\ \mathcal{A}\end{pmatrix}$$

$$\begin{aligned}
A_{11} &= +(2/3)\alpha K+(2/3)\alpha\mathcal{A}+\beta^k\partial_k\\
A_{12} &= -4e^{-4\varphi}\alpha(\partial_k\varphi)\tilde\gamma^{kj}-2e^{-4\varphi}(\partial_k\alpha)\tilde\gamma^{jk}\\
A_{13} &= -2\alpha e^{-4\varphi}\tilde A^k{}_j\partial_k-\alpha e^{-4\varphi}(\partial_j\tilde A_{kl})\tilde\gamma^{kl}-e^{-4\varphi}(\partial_j\alpha)\mathcal{A}-e^{-4\varphi}\beta^k\partial_k\partial_j-(1/2)e^{-4\varphi}\beta^k\tilde\gamma^{-1}(\partial_j\mathcal{S})\partial_k\\
&\quad +(1/6)e^{-4\varphi}\tilde\gamma^{-1}(\partial_j\beta^k)(\partial_k\mathcal{S})-(2/3)e^{-4\varphi}(\partial_k\beta^k)\partial_j\\
A_{14} &= 2\alpha e^{-4\varphi}\tilde\gamma^{-1}\tilde\gamma^{lk}(\partial_l\varphi)\mathcal{A}\partial_k+(1/2)\alpha e^{-4\varphi}\tilde\gamma^{-1}(\partial_l\mathcal{A})\tilde\gamma^{lk}\partial_k+(1/2)e^{-4\varphi}\tilde\gamma^{-1}(\partial_l\alpha)\tilde\gamma^{lk}\mathcal{A}\partial_k+(1/2)e^{-4\varphi}\tilde\gamma^{-1}\beta^m\tilde\gamma^{lk}\partial_m\partial_l\partial_k\\
&\quad -(5/4)e^{-4\varphi}\tilde\gamma^{-2}\beta^m\tilde\gamma^{lk}(\partial_m\mathcal{S})\partial_l\partial_k+e^{-4\varphi}\tilde\gamma^{-1}\beta^m(\partial_m\tilde\gamma^{lk})\partial_l\partial_k+(1/2)e^{-4\varphi}\tilde\gamma^{-1}\beta^i(\partial_j\partial_i\tilde\gamma^{jk})\partial_k\\
&\quad +(3/4)e^{-4\varphi}\tilde\gamma^{-3}\beta^i\tilde\gamma^{jk}(\partial_i\mathcal{S})(\partial_j\mathcal{S})\partial_k-(3/4)e^{-4\varphi}\tilde\gamma^{-2}\beta^i(\partial_i\tilde\gamma^{jk})(\partial_j\mathcal{S})\partial_k+(1/3)e^{-4\varphi}\tilde\gamma^{-1}\tilde\gamma^{pj}(\partial_j\beta^k)\partial_p\partial_k\\
&\quad -(5/12)e^{-4\varphi}\tilde\gamma^{-2}\tilde\gamma^{jk}(\partial_k\beta^i)(\partial_i\mathcal{S})\partial_j+(1/3)e^{-4\varphi}\tilde\gamma^{-1}(\partial_k\tilde\gamma^{ij})(\partial_j\beta^k)\partial_i-(1/6)e^{-4\varphi}\tilde\gamma^{-1}\tilde\gamma^{mk}(\partial_k\partial_l\beta^l)\partial_m\\
A_{15} &= (4/9)\alpha K\mathcal{A}-(8/9)\alpha K^2+(4/3)\alpha e^{-4\varphi}(\partial_i\partial_j\varphi)\tilde\gamma^{ij}+(8/3)\alpha e^{-4\varphi}(\partial_k\varphi)(\partial_l\tilde\gamma^{lk})+\alpha e^{-4\varphi}(\partial_j\tilde\gamma^{jk})\partial_k\\
&\quad +8\alpha e^{-4\varphi}\tilde\gamma^{jk}(\partial_j\varphi)\partial_k+\alpha e^{-4\varphi}\tilde\gamma^{jk}\partial_j\partial_k+8e^{-4\varphi}(\partial_l\alpha)(\partial_k\varphi)\tilde\gamma^{lk}+e^{-4\varphi}(\partial_l\alpha)(\partial_k\tilde\gamma^{lk})+2e^{-4\varphi}(\partial_l\alpha)\tilde\gamma^{lk}\partial_k\\
&\quad +e^{-4\varphi}\tilde\gamma^{lk}(\partial_l\partial_k\alpha)\\
A_{23} &= \alpha e^{-4\varphi}\tilde\gamma^{km}(\partial_k\varphi)(\partial_j\tilde\gamma_{mi})-(1/2)\alpha e^{-4\varphi}\tilde\Gamma^m_{kl}\tilde\gamma^{kl}(\partial_j\tilde\gamma_{mi})\\
&\quad +(1/2)\alpha e^{-4\varphi}\tilde\gamma^{mk}(\partial_k\partial_j\tilde\gamma_{mi})+(1/2)\alpha e^{-4\varphi}\tilde\gamma^{-2}(\partial_i\mathcal{S})(\partial_j\mathcal{S})-(1/4)\alpha e^{-4\varphi}(\partial_i\tilde\gamma_{kl})(\partial_j\tilde\gamma^{kl})+\alpha e^{-4\varphi}\tilde\gamma^{km}(\partial_k\varphi)\tilde\gamma_{ji}\partial_m\\
&\quad +\alpha e^{-4\varphi}(\partial_j\varphi)\partial_i-(1/2)\alpha e^{-4\varphi}\tilde\Gamma^m_{kl}\tilde\gamma^{kl}\tilde\gamma_{ji}\partial_m+\alpha e^{-4\varphi}\tilde\gamma^{mk}\tilde\Gamma_{ijk}\partial_m+(1/2)\alpha e^{-4\varphi}\tilde\gamma^{lk}\tilde\gamma_{ji}\partial_k\partial_l\\
&\quad +(1/2)e^{-4\varphi}\tilde\gamma^{mk}(\partial_j\tilde\gamma_{im})(\partial_k\alpha)+(1/2)e^{-4\varphi}(\partial_j\alpha)\partial_i+(1/2)e^{-4\varphi}\tilde\gamma^{mk}\tilde\gamma_{ji}(\partial_k\alpha)\partial_m\\
A_{25} &= -\tilde A^k{}_i(\partial_k\alpha)+(1/9)(\partial_i\alpha)K+(4/9)\alpha(\partial_iK)+(1/9)\alpha K\partial_i-\alpha\tilde A^k{}_i\partial_k\\
A_{34} &= -(1/2)\beta^k\tilde\gamma^{il}\tilde\gamma^{-2}(\partial_l\mathcal{S})\partial_k-(1/2)(\partial_l\beta^i)\tilde\gamma^{lk}\tilde\gamma^{-1}\partial_k+(1/3)(\partial_l\beta^l)\tilde\gamma^{ik}\tilde\gamma^{-1}\partial_k-(1/2)\beta^l\tilde\gamma^{in}(\partial_l\tilde\gamma_{mn})\tilde\gamma^{mk}\tilde\gamma^{-1}\partial_k\\
&\quad +(1/2)\beta^k\tilde\gamma^{il}\tilde\gamma^{-1}\partial_l\partial_k\\
A_{35} &= -(\partial_k\alpha)\tilde\gamma^{ik}+4\alpha\tilde\gamma^{ik}(\partial_k\varphi)-\alpha\tilde\gamma^{ik}\partial_k
\end{aligned}$$

BSSN Constraint propagation analysis in flat spacetime

- The set of the constraint propagation equations, $\partial_t(\mathcal{H}^{BSSN}, \mathcal{M}_i, \mathcal{G}^i, \mathcal{A}, \mathcal{S})^T$?

- For the flat background metric $g_{\mu\nu} = \eta_{\mu\nu}$, the first order perturbation equations of (6)-(10):

$$\begin{aligned}
\partial_t {}^{(1)}\varphi &= -(1/6){}^{(1)}K + (1/6)\kappa_\varphi {}^{(1)}\mathcal{A} && (11)\\
\partial_t {}^{(1)}\tilde{\gamma}_{ij} &= -2{}^{(1)}\tilde{A}_{ij} - (2/3)\kappa_{\tilde{\gamma}}\delta_{ij}{}^{(1)}\mathcal{A} && (12)\\
\partial_t {}^{(1)}K &= -(\partial_j\partial_j{}^{(1)}\alpha) + \kappa_{K1}\partial_j{}^{(1)}\mathcal{G}^j - \kappa_{K2}{}^{(1)}\mathcal{H}^{BSSN} && (13)\\
\partial_t {}^{(1)}\tilde{A}_{ij} &= {}^{(1)}(R^{BSSN}_{ij})^{TF} - {}^{(1)}(\tilde{D}_i\tilde{D}_j\alpha)^{TF} + \kappa_{A1}\delta_{k(i}(\partial_{j)}{}^{(1)}\mathcal{G}^k) - (1/3)\kappa_{A2}\delta_{ij}(\partial_k{}^{(1)}\mathcal{G}^k) && (14)\\
\partial_t {}^{(1)}\tilde{\Gamma}^i &= -(4/3)(\partial_i{}^{(1)}K) - (2/3)\kappa_{\tilde{\Gamma}1}(\partial_i{}^{(1)}\mathcal{A}) + 2\kappa_{\tilde{\Gamma}2}{}^{(1)}\mathcal{M}_i && (15)
\end{aligned}$$

We express the adjustements as

$$\kappa_{adj} := (\kappa_\varphi, \kappa_{\tilde{\gamma}}, \kappa_{K1}, \kappa_{K2}, \kappa_{A1}, \kappa_{A2}, \kappa_{\tilde{\Gamma}1}, \kappa_{\tilde{\Gamma}2}). \quad (16)$$

- Constraint propagation equations at the first order in the flat spacetime:

$$\begin{aligned}
\partial_t {}^{(1)}\mathcal{H}^{BSSN} &= (\kappa_{\tilde{\gamma}} - (2/3)\kappa_{\tilde{\Gamma}1} - (4/3)\kappa_\varphi + 2)\,\partial_j\partial_j{}^{(1)}\mathcal{A} + 2(\kappa_{\tilde{\Gamma}2} - 1)(\partial_j{}^{(1)}\mathcal{M}_j), && (17)\\
\partial_t {}^{(1)}\mathcal{M}_i &= (-(2/3)\kappa_{K1} + (1/2)\kappa_{A1} - (1/3)\kappa_{A2} + (1/2))\,\partial_i\partial_j{}^{(1)}\mathcal{G}^j \\
&\quad + (1/2)\kappa_{A1}\partial_j\partial_j{}^{(1)}\mathcal{G}^i + ((2/3)\kappa_{K2} - (1/2))\,\partial_i{}^{(1)}\mathcal{H}^{BSSN}, && (18)\\
\partial_t {}^{(1)}\mathcal{G}^i &= 2\kappa_{\tilde{\Gamma}2}{}^{(1)}\mathcal{M}_i + (-(2/3)\kappa_{\tilde{\Gamma}1} - (1/3)\kappa_{\tilde{\gamma}})(\partial_i{}^{(1)}\mathcal{A}), && (19)\\
\partial_t {}^{(1)}\mathcal{S} &= -2\kappa_{\tilde{\gamma}}{}^{(1)}\mathcal{A}, && (20)\\
\partial_t {}^{(1)}\mathcal{A} &= (\kappa_{A1} - \kappa_{A2})(\partial_j{}^{(1)}\mathcal{G}^j). && (21)
\end{aligned}$$

Effect of adjustments

No.		Constraints (number of components) $\mathcal{H}$ (1)	$\mathcal{M}_i$ (3)	$\mathcal{G}^i$ (3)	$\mathcal{A}$ (1)	$\mathcal{S}$ (1)	diag?	Constr. Amp. Factors in Minkowskii background
0.	standard ADM	use	use	-	-	-	yes	$(0, 0, \Im, \Im)$
1.	BSSN no adjustment	use	use	use	use	use	yes	$(0, 0, 0, 0, 0, 0, 0, \Im, \Im)$
2.	the BSSN	use+adj	use+adj	use+adj	use+adj	use+adj	no	$(0, 0, 0, \Im, \Im, \Im, \Im, \Im, \Im)$
3.	no $\mathcal{S}$ adjustment	use+adj	use+adj	use+adj	use+adj	use	no	no difference in flat background
4.	no $\mathcal{A}$ adjustment	use+adj	use+adj	use+adj	use	use+adj	no	$(0, 0, 0, \Im, \Im, \Im, \Im, \Im, \Im)$
5.	no $\mathcal{G}^i$ adjustment	use+adj	use+adj	use	use+adj	use+adj	no	$(0, 0, 0, 0, 0, 0, 0, \Im, \Im)$
6.	no $\mathcal{M}_i$ adjustment	use+adj	use	use+adj	use+adj	use+adj	no	$(0, 0, 0, 0, 0, 0, 0, \Re, \Re)$ Growing modes
7.	no $\mathcal{H}$ adjustment	use	use+adj	use+adj	use+adj	use+adj	no	$(0, 0, 0, \Im, \Im, \Im, \Im, \Im, \Im)$
8.	ignore $\mathcal{G}^i$, $\mathcal{A}$, $\mathcal{S}$	use+adj	use+adj	-	-	-	no	$(0, 0, 0, 0)$
9.	ignore $\mathcal{G}^i$, $\mathcal{A}$	use+adj	use+adj	use+adj	-	-	yes	$(0, \Im, \Im, \Im, \Im, \Im, \Im)$
10.	ignore $\mathcal{G}^i$	use+adj	use+adj	-	use+adj	use+adj	no	$(0, 0, 0, 0, 0, 0)$
11.	ignore $\mathcal{A}$	use+adj	use+adj	use+adj	-	use+adj	yes	$(0, 0, \Im, \Im, \Im, \Im, \Im, \Im)$
12.	ignore $\mathcal{S}$	use+adj	use+adj	use+adj	use+adj	-	yes	$(0, 0, \Im, \Im, \Im, \Im, \Im, \Im)$

TRS breaking adjustments

In order to break time reversal symmetry (TRS) of the evolution eqs, to adjust $\partial_t\phi$,$\partial_t\tilde\gamma_{ij}$,$\partial_t\tilde\Gamma^i$ using $\mathcal{S}, \mathcal{G}^i$, or to adjust $\partial_t K, \partial_t \tilde A_{ij}$ using $\tilde{\mathcal{A}}$.

$$
\begin{aligned}
\partial_t\phi &= \partial_t^{BS}\phi + \kappa_{\phi\mathcal{H}}\alpha\mathcal{H}^{BS} + \kappa_{\phi\mathcal{G}}\alpha\tilde D_k\mathcal{G}^k + \kappa_{\phi\mathcal{S}1}\alpha\mathcal{S} + \kappa_{\phi\mathcal{S}2}\alpha\tilde D^j\tilde D_j\mathcal{S}\\
\partial_t\tilde\gamma_{ij} &= \partial_t^{BS}\tilde\gamma_{ij} + \kappa_{\tilde\gamma\mathcal{H}}\alpha\tilde\gamma_{ij}\mathcal{H}^{BS} + \kappa_{\tilde\gamma\mathcal{G}1}\alpha\tilde\gamma_{ij}\tilde D_k\mathcal{G}^k + \kappa_{\tilde\gamma\mathcal{G}2}\alpha\tilde\gamma_{k(i}\tilde D_{j)}\mathcal{G}^k + \kappa_{\tilde\gamma\mathcal{S}1}\alpha\tilde\gamma_{ij}\mathcal{S} + \kappa_{\tilde\gamma\mathcal{S}2}\alpha\tilde D_i\tilde D_j\mathcal{S}\\
\partial_t K &= \partial_t^{BS}K + \kappa_{K\mathcal{M}}\alpha\tilde\gamma^{jk}(\tilde D_j\mathcal{M}_k) + \kappa_{K\tilde{\mathcal{A}}1}\alpha\tilde{\mathcal{A}} + \kappa_{K\tilde{\mathcal{A}}2}\alpha\tilde D^j\tilde D_j\tilde{\mathcal{A}}\\
\partial_t\tilde A_{ij} &= \partial_t^{BS}\tilde A_{ij} + \kappa_{A\mathcal{M}1}\alpha\tilde\gamma_{ij}(\tilde D^k\mathcal{M}_k) + \kappa_{A\mathcal{M}2}\alpha(\tilde D_{(i}\mathcal{M}_{j)}) + \kappa_{A\tilde{\mathcal{A}}1}\alpha\tilde\gamma_{ij}\tilde{\mathcal{A}} + \kappa_{A\tilde{\mathcal{A}}2}\alpha\tilde D_i\tilde D_j\tilde{\mathcal{A}}\\
\partial_t\tilde\Gamma^i &= \partial_t^{BS}\tilde\Gamma^i + \kappa_{\tilde\Gamma\mathcal{H}}\alpha\tilde D^i\mathcal{H}^{BS} + \kappa_{\tilde\Gamma\mathcal{G}1}\alpha\mathcal{G}^i + \kappa_{\tilde\Gamma\mathcal{G}2}\alpha\tilde D^j\tilde D_j\mathcal{G}^i + \kappa_{\tilde\Gamma\mathcal{G}3}\alpha\tilde D^i\tilde D_j\mathcal{G}^j + \kappa_{\tilde\Gamma\mathcal{S}}\alpha\tilde D^i\mathcal{H}^{BS}
\end{aligned}
$$

or in the flat background

$$
\begin{aligned}
\partial_t^{ADJ(1)}\phi &= +\kappa_{\phi\mathcal{H}}{}^{(1)}\mathcal{H}^{BS} + \kappa_{\phi\mathcal{G}}\partial_k{}^{(1)}\mathcal{G}^k + \kappa_{\phi\mathcal{S}1}{}^{(1)}\mathcal{S} + \kappa_{\phi\mathcal{S}2}\partial_j\partial_j{}^{(1)}\mathcal{S}\\
\partial_t^{ADJ(1)}\tilde\gamma_{ij} &= +\kappa_{\tilde\gamma\mathcal{H}}\delta_{ij}{}^{(1)}\mathcal{H}^{BS} + \kappa_{\tilde\gamma\mathcal{G}1}\delta_{ij}\partial_k{}^{(1)}\mathcal{G}^k + (1/2)\kappa_{\tilde\gamma\mathcal{G}2}(\partial_j{}^{(1)}\mathcal{G}^i + \partial_i{}^{(1)}\mathcal{G}^j) + \kappa_{\tilde\gamma\mathcal{S}1}\delta_{ij}{}^{(1)}\mathcal{S} + \kappa_{\tilde\gamma\mathcal{S}2}\partial_i\partial_j{}^{(1)}\mathcal{S}\\
\partial_t^{ADJ(1)}K &= +\kappa_{K\mathcal{M}}\partial_j{}^{(1)}\mathcal{M}_j + \kappa_{K\tilde{\mathcal{A}}1}{}^{(1)}\tilde{\mathcal{A}} + \kappa_{K\tilde{\mathcal{A}}2}\partial_j\partial_j{}^{(1)}\tilde{\mathcal{A}}\\
\partial_t^{ADJ(1)}\tilde A_{ij} &= +\kappa_{A\mathcal{M}1}\delta_{ij}\partial_k{}^{(1)}\mathcal{M}_k + (1/2)\kappa_{A\mathcal{M}2}(\partial_i\mathcal{M}_j + \partial_j\mathcal{M}_i) + \kappa_{A\tilde{\mathcal{A}}1}\delta_{ij}\tilde{\mathcal{A}} + \kappa_{A\tilde{\mathcal{A}}2}\partial_i\partial_j\tilde{\mathcal{A}}\\
\partial_t^{ADJ(1)}\tilde\Gamma^i &= +\kappa_{\tilde\Gamma\mathcal{H}}\partial_i{}^{(1)}\mathcal{H}^{BS} + \kappa_{\tilde\Gamma\mathcal{G}1}{}^{(1)}\mathcal{G}^i + \kappa_{\tilde\Gamma\mathcal{G}2}\partial_j\partial_j{}^{(1)}\mathcal{G}^i + \kappa_{\tilde\Gamma\mathcal{G}3}\partial_i\partial_j{}^{(1)}\mathcal{G}^j + \kappa_{\tilde\Gamma\mathcal{S}}\partial_i{}^{(1)}\mathcal{S}
\end{aligned}
$$

Constraint Amplification Factors with each adjustment

adjustment		CAFs	diag?	effect of the adjustment
$\partial_t \phi$	$\kappa_{\phi\mathcal{H}}\, \alpha \mathcal{H}$	$(0,0,\pm\sqrt{-k^2}(*3), 8\kappa_{\phi\mathcal{H}}k^2)$	no	$\kappa_{\phi\mathcal{H}} < 0$ makes 1 Neg.
$\partial_t \phi$	$\kappa_{\phi\mathcal{G}}\, \alpha \tilde{D}_k \mathcal{G}^k$	$(0,0,\pm\sqrt{-k^2}(*2)$, long expressions)	yes	$\kappa_{\phi\mathcal{G}} < 0$ makes 2 Neg. 1 Pos.
$\partial_t \tilde{\gamma}_{ij}$	$\kappa_{SD}\, \alpha \tilde{\gamma}_{ij} \mathcal{H}$	$(0,0,\pm\sqrt{-k^2}(*3), (3/2)\kappa_{SD}k^2)$	yes	$\kappa_{SD} < 0$ makes 1 Neg. Case (B)
$\partial_t \tilde{\gamma}_{ij}$	$\kappa_{\tilde{\gamma}\mathcal{G}1}\, \alpha \tilde{\gamma}_{ij} \tilde{D}_k \mathcal{G}^k$	$(0,0,\pm\sqrt{-k^2}(*2)$, long expressions)	yes	$\kappa_{\tilde{\gamma}\mathcal{G}1} > 0$ makes 1 Neg.
$\partial_t \tilde{\gamma}_{ij}$	$\kappa_{\tilde{\gamma}\mathcal{G}2}\, \alpha \tilde{\gamma}_{k(i} \tilde{D}_{j)} \mathcal{G}^k$	(0,0, $(1/4)k^2\kappa_{\tilde{\gamma}\mathcal{G}2} \pm \sqrt{k^2(-1+k^2\kappa_{\tilde{\gamma}\mathcal{G}2}/16)}(*2)$, long expressions)	yes	$\kappa_{\tilde{\gamma}\mathcal{G}2} < 0$ makes 6 Neg. 1 Pos. Case (E1)
$\partial_t \tilde{\gamma}_{ij}$	$\kappa_{\tilde{\gamma}\mathcal{S}1}\, \alpha \tilde{\gamma}_{ij} \mathcal{S}$	$(0,0,\pm\sqrt{-k^2}(*3), 3\kappa_{\tilde{\gamma}\mathcal{S}1})$	no	$\kappa_{\tilde{\gamma}\mathcal{S}1} < 0$ makes 1 Neg.
$\partial_t \tilde{\gamma}_{ij}$	$\kappa_{\tilde{\gamma}\mathcal{S}2}\, \alpha \tilde{D}_i \tilde{D}_j \mathcal{S}$	$(0,0,\pm\sqrt{-k^2}(*3), -\kappa_{\tilde{\gamma}\mathcal{S}2}k^2)$	no	$\kappa_{\tilde{\gamma}\mathcal{S}2} > 0$ makes 1 Neg.
$\partial_t K$	$\kappa_{K\mathcal{M}}\, \alpha \tilde{\gamma}^{jk} (\tilde{D}_j \mathcal{M}_k)$	$(0,0,0,\pm\sqrt{-k^2}(*2),$ $(1/3)\kappa_{K\mathcal{M}}k^2 \pm (1/3)\sqrt{k^2(-9+k^2\kappa_{K\mathcal{M}}^2)})$	no	$\kappa_{K\mathcal{M}} < 0$ makes 2 Neg.
$\partial_t \tilde{A}_{ij}$	$\kappa_{A\mathcal{M}1}\, \alpha \tilde{\gamma}_{ij} (\tilde{D}^k \mathcal{M}_k)$	$(0,0,\pm\sqrt{-k^2}(*3), -\kappa_{A\mathcal{M}1}k^2)$	yes	$\kappa_{A\mathcal{M}1} > 0$ makes 1 Neg.
$\partial_t \tilde{A}_{ij}$	$\kappa_{A\mathcal{M}2}\, \alpha (\tilde{D}_{(i} \mathcal{M}_{j)})$	(0,0, $-k^2\kappa_{A\mathcal{M}2}/4 \pm \sqrt{k^2(-1+k^2\kappa_{A\mathcal{M}2}/16)}(*2)$, long expressions)	yes	$\kappa_{A\mathcal{M}2} > 0$ makes 7 Neg Case (D)
$\partial_t \tilde{A}_{ij}$	$\kappa_{A\mathcal{A}1}\, \alpha \tilde{\gamma}_{ij} \mathcal{A}$	$(0,0,\pm\sqrt{-k^2}(*3), 3\kappa_{A\mathcal{A}1})$	yes	$\kappa_{A\mathcal{A}1} < 0$ makes 1 Neg.
$\partial_t \tilde{A}_{ij}$	$\kappa_{A\mathcal{A}2}\, \alpha \tilde{D}_i \tilde{D}_j \mathcal{A}$	$(0,0,\pm\sqrt{-k^2}(*3), -\kappa_{A\mathcal{A}2}k^2)$	yes	$\kappa_{A\mathcal{A}2} > 0$ makes 1 Neg.
$\partial_t \tilde{\Gamma}^i$	$\kappa_{\tilde{\Gamma}\mathcal{H}}\, \alpha \tilde{D}^i \mathcal{H}$	$(0,0,\pm\sqrt{-k^2}(*3), -\kappa_{A\mathcal{A}2}k^2)$	no	$\kappa_{\tilde{\Gamma}\mathcal{H}} > 0$ makes 1 Neg.
$\partial_t \tilde{\Gamma}^i$	$\kappa_{\tilde{\Gamma}\mathcal{G}1}\, \alpha \mathcal{G}^i$	$(0,0,(1/2)\kappa_{\tilde{\Gamma}\mathcal{G}1} \pm \sqrt{-k^2+\kappa_{\tilde{\Gamma}\mathcal{G}1}^2}(*2)$, long.)	yes	$\kappa_{\tilde{\Gamma}\mathcal{G}1} < 0$ makes 6 Neg. 1 Pos. Case (E2)
$\partial_t \tilde{\Gamma}^i$	$\kappa_{\tilde{\Gamma}\mathcal{G}2}\, \alpha \tilde{D}^j \tilde{D}_j \mathcal{G}^i$	$(0,0,-(1/2)\kappa_{\tilde{\Gamma}\mathcal{G}2} \pm \sqrt{-k^2+\kappa_{\tilde{\Gamma}\mathcal{G}2}^2}(*2)$, long.)	yes	$\kappa_{\tilde{\Gamma}\mathcal{G}2} > 0$ makes 2 Neg. 1 Pos.
$\partial_t \tilde{\Gamma}^i$	$\kappa_{\tilde{\Gamma}\mathcal{G}3}\, \alpha \tilde{D}^i \tilde{D}_j \mathcal{G}^j$	$(0,0,-(1/2)\kappa_{\tilde{\Gamma}\mathcal{G}3} \pm \sqrt{-k^2+\kappa_{\tilde{\Gamma}\mathcal{G}3}^2}(*2)$, long.)	yes	$\kappa_{\tilde{\Gamma}\mathcal{G}3} > 0$ makes 2 Neg. 1 Pos.

Comparisons of Adjusted BSSN systems (linear wave)

Mexico NR 2002 Workshop participants

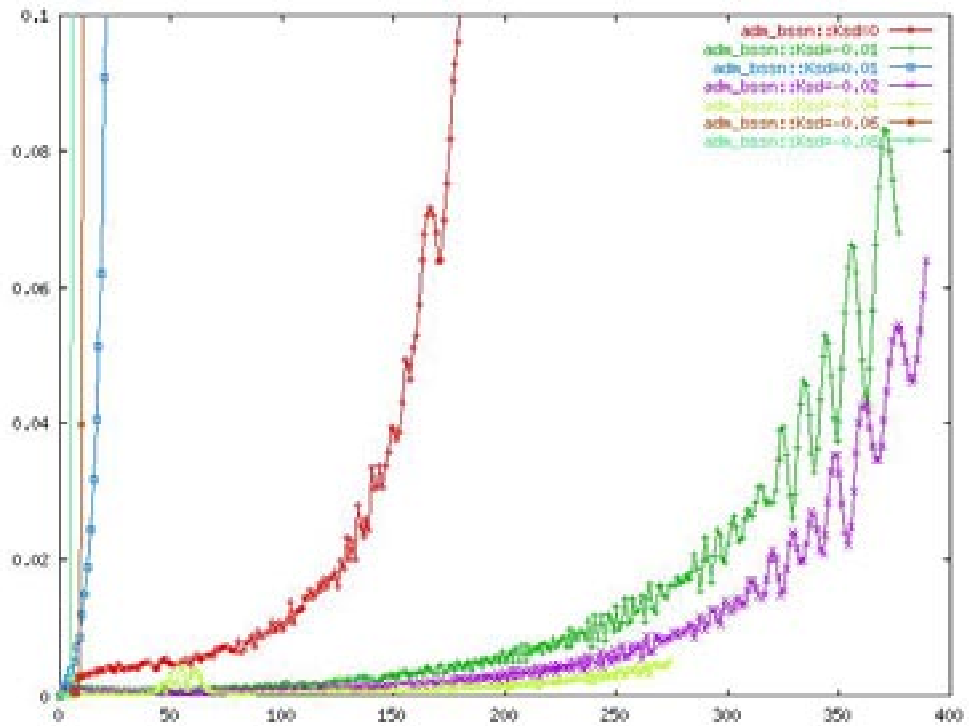
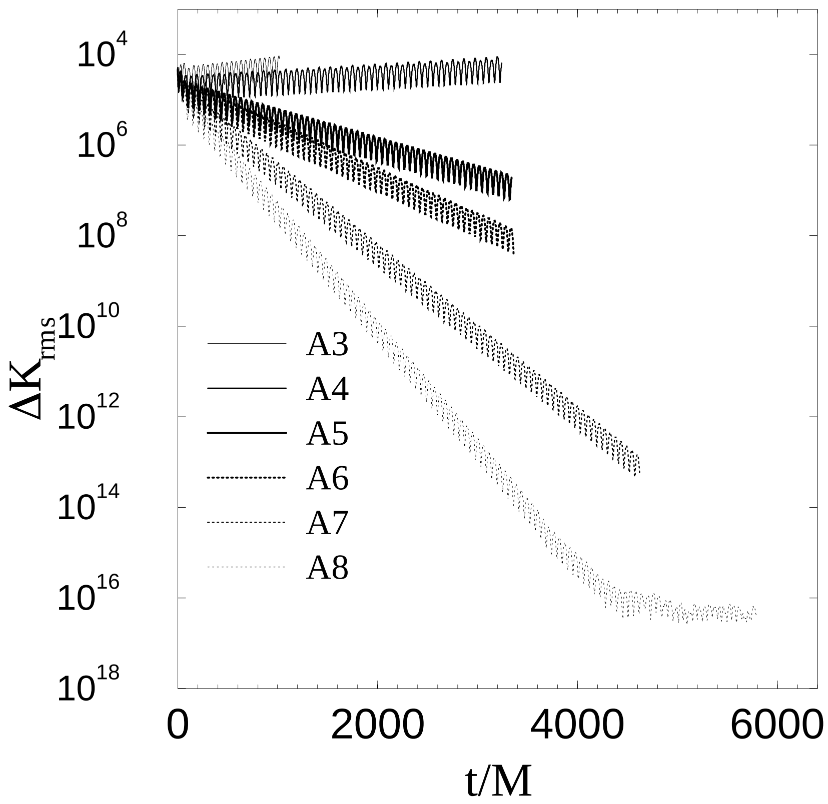
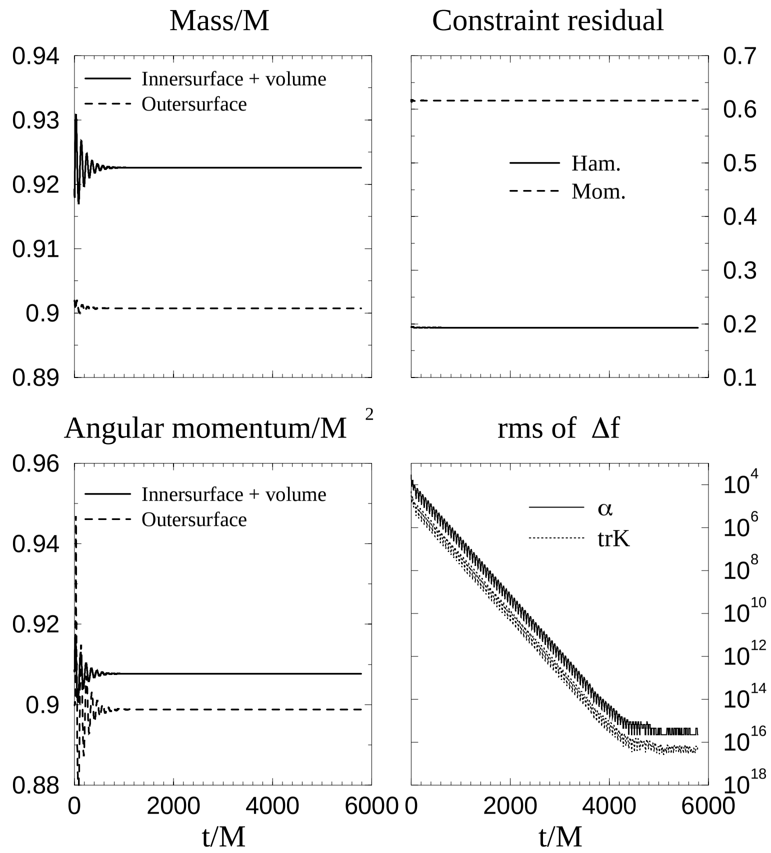


Figure 2: Violation of Hamiltonian constraints versus time: Adjusted BSSN systems applied for Teukolsky wave initial data evolution with harmonic slicing, and with periodic boundary condition. Cactus/AEIThorns/BSSN code was used. Grid $= 24^3$, $\Delta x = 0.25$, iterative Crank-Nicholson method. Courtesy of N. Dorband and D. Pollney (AEI).

An Evolution of Adjusted BSSN Formulation

by Yo-Baumgarte-Shapiro, gr-qc/0209066





Kerr-Schild BH (0.9 J/M), excision with cube, $1+\log$-lapse, Γ-driver shift.

$$\partial_t \tilde\Gamma^i = (\cdots) + \frac{2}{3}\tilde\Gamma^i \beta^i{}_{,j} - (\chi + \frac{2}{3})\mathcal{G}^i \beta^j{}_{,j} \qquad \chi = 2/3 \ \ \textbf{for (A4)-(A8)}$$

$$\partial_t \tilde\gamma_{ij} = (\cdots) - \kappa\alpha\tilde\gamma_{ij}\mathcal{H} \qquad \kappa = 0.1 \sim 0.2 \ \ \textbf{for (A5), (A6) and (A8)}$$

Summary

Towards a stable and accurate formulation for numerical relativity

- Several reports say numerical stabilities depend on the formulations to apply, although they are mathematically equivalent.
- status = chaotic, many trials and errors
  We tried to understand the background in an unified way.
- Our proposal = "Evaluate eigenvalues of constraint propagation eqns"
  We give satisfactory conditions for stable evolutions.
  Fourier transformation allows to discuss lower-order terms.
- Our Observation = "Stability will change by adding constraints in RHS"
  We named "Adjusted System".
  Numerically confirmed in the Maxwell system and Ashtekar system.
- Our Observation 2= The idea works even for the ADM formulation
  We explain the effective parameter range of Detweiler's system (1987).
  We proposed variety of adjustments. Several numerical confirmations.
- Our Observation 3= The idea works also for the BSSN formulation
  We explain why adjusting momentum constraints improves the stability.
  We proposed variety of adjustments. Several numerical confirmations.

Evaluation of CAFs may be an alternative guideline to hyperbolization of the system.

Next Steps?

- Generalize the procedure to construct adjusted systems
  - dynamical and automatical determination of κ under a suitable principle.
  - target to control each constraint violation by adjusting multipliers.
  - clarify the reasons of non-linear violation in current test evolutions.
- More on hyperbolic formulations
  - effects of non-principal part?
  - clarify the reasons of advantages of kinematic parameters (in KST) mixed-form variables, and/or densitized lapse?
  - links to the initial-boundary value problem (IBVP).
- Alternative new ideas?
  - control theories, optimization methods (convex functional theories), mathematical programming methods, or ....
- Numerical comparisons of formulations
  - "Comparisons of Formulations of Einstein's equations for Numerical Relativity" (Mexico NR workshop, 2002) in progress

Kidder-Scheel-Teukolsky hyperbolic formulation (Anderson-York + Frittelli-Reula)

Phys. Rev. D. 64 (2001) 064017

- Construct a First-order form using variables $(K_{ij}, g_{ij}, d_{kij})$ where $d_{kij} \equiv \partial_k g_{ij}$
  Constraints are $(\mathcal{H}, \mathcal{M}_i, \mathcal{C}_{kij}, \mathcal{C}_{klij})$ where $\mathcal{C}_{kij} \equiv d_{kij} - \partial_k g_{ij}$, and $\mathcal{C}_{klij} \equiv \partial_{[k} d_{l]ij}$
- Densitize the lapse, $Q = \log(N g^{-\sigma})$
- Adjust equations with constraints

$$\begin{aligned}
\hat{\partial}_0 g_{ij} &= -2NK_{ij} \\
\hat{\partial}_0 K_{ij} &= (\cdots) + \gamma N g_{ij}\mathcal{H} + \zeta N g^{ab}\mathcal{C}_{a(ij)b} \\
\hat{\partial}_0 d_{kij} &= (\cdots) + \eta N g_{k(i}\mathcal{M}_{j)} + \chi N g_{ij}\mathcal{M}_k
\end{aligned}$$

- Re-deining the variables $(P_{ij}, g_{ij}, M_{kij})$

$$\begin{aligned}
P_{ij} &\equiv K_{ij} + \hat{z} g_{ij} K, \\
M_{kij} &\equiv (1/2)[\hat{k} d_{kij} + \hat{e} d_{(ij)k} + g_{ij}(\hat{a} d_k + \hat{b} b_k) + g_{k(i}(\hat{c} d_{j)} + \hat{d} b_{j)})], \quad d_k = g^{ab} d_{kab}, b_k = g^{ab} d_{abk}
\end{aligned}$$

The redefinition parameters

- do not change the eigenvalues of evolution eqs.
- do not effect on the principal part of the constraint evolution eqs.
- do affect the eigenvectors of evolution system.
- do affect nonlinear terms of evolution eqs/constraint evolution eqs.